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## A Finite Difference Analogue to the Problem of Zofia Szmydt

Analogon problemu Zofii Szmydt w metodzie różnic skończonych

Аналог проблемы Софии Шмыдт в методе конечных разностей

In this paper we will consider a finite difference approximation of the well-known Z. Szmydt problem (cf. [3], e.g.). To do this we use an operator calculus found in [6]. This is another example for the possibility of an unified treatment of differential and difference problems proposed in [9].

1. Elements of an operator calculus. Let be given the linear spaces $L^{0}$ and $L^{1}$. According to [6] we fix the following definitions and statements.

Definition 1. An operator $S$ belonging to $L\left(L^{1}, L^{0}\right)$ with $S\left(L^{1}\right)=L^{0}$ is called an (algebraic) derivative. Each operator $T \in L\left(L^{0}, L^{i}\right)$ which satisfies $S T=$ id $\left.\right|_{L^{\circ}}$ is called an (algebraic) integral with respect to $S$. The operator $s=$ id $\left.\right|_{L^{\prime}}-T S$ is then the boundary condition corresponding to $S$ and $T$.

Theorem 1. The differential equation problem
(1)

$$
S u=f, f \in L^{0}
$$

$$
s u=u_{0}, u_{0} \in \operatorname{Ker} S
$$

## has the solution

(2)

$$
u=u_{0}+T f .
$$

We will omit examples to illustrate the notions above, they will be found in [6] or [5].
Suppose that there are given two isomorphic mappings $\psi_{0}: L^{0} \rightarrow \bar{L}^{0}$ and $\psi_{1}: L^{1} \rightarrow$ $\rightarrow \bar{L}^{1}$, where $\bar{L}^{0}$ and $\bar{L}^{1}$ are linear spaces, too.

Definition 2. The operator $\bar{S}=\psi_{0} S \psi_{1}^{-1}, \bar{T}=\psi_{1} T \psi_{0}^{-1}$ and $\bar{s}=\psi_{1} s \psi_{1}^{1}$ will be called equivalent derivative, integral and boundary condition with respect to $S, T$ and $s$.

Theorem 2. Problem (1) is equivalent to
(3)

$$
\bar{S} \bar{u}=\bar{f}_{0} \bar{f}=\psi_{0} f \in \bar{L}^{0}
$$

$$
\bar{s} \bar{u}=\bar{u}_{0}, \bar{u}_{0}=\psi_{1} \bar{u}_{0} \in \operatorname{Ker} \bar{S} .
$$

The image of (2) with respect to $\psi_{1}$ is the unique solution of this problem.
2. Preliminary definitions and results. Let us denote by $D\left(R^{2}\right)$ the space $C_{0}^{\infty}\left(R^{2}\right)$ with the usual topology. By $D^{\prime}\left(R^{2}\right)$ we realize the space of linear and continuous functionals on $D\left(R^{2}\right)$. The elements of $D^{\prime}\left(R^{2}\right)$ are called distributions. For details in notions and theorems see [7], e.g. We will consider the following problem: Find a distribution $u^{(h)}$ satisfying

$$
\begin{equation*}
\bar{\partial}_{\xi} \bar{\partial}_{\eta} u^{(h)}=f(\xi, \eta), f \in D^{\prime}\left(R^{2}\right) \tag{4}
\end{equation*}
$$

where the distribution $\bar{\partial}_{\xi} \bar{\partial}_{\eta} u^{(h)}$ is defined by

$$
\left(\bar{\partial} \xi \bar{\partial}_{\eta} u^{(h)}, \phi\right)=\left(u^{(h)}, \partial \xi \partial \eta \phi\right), \phi \in D\left(R^{2}\right)
$$

with $(\partial \xi \partial \eta \phi)(\xi, \eta)=\left(\phi_{h}^{h}(\xi, \eta)-\phi_{h}(\xi, \eta)-\phi^{h}(\xi, \eta)+\phi(\xi, \eta)\right) / h^{2}, h>0$ is a discretization parameter. We used the abbreviation $\phi_{k h}^{j h}(\xi, \eta)=\phi(\xi+k h, \eta+j h), j$ and $k$ are integers.

Problem (4) is an approximation of

$$
\begin{equation*}
u_{\xi \eta}^{\prime \prime}=f(\xi, \eta) \tag{5}
\end{equation*}
$$

and must be interpreted as a suitable extension of the usual numerical problem

$$
u_{k, j}^{(h)}-u_{k-1, j}^{(h)}-u_{k, j-1}^{(h)}+u_{k-1, j-1}^{(h)}=h^{2} f(k h, j h),
$$

which is a possible discretization of (5) by backward finite difference formulaes using $h$ as a discretization parameter for both directions. We are interested in boundary conditions assuring existence and uniqueness of solutions of (4).

Definition 3. The distribution $E^{(h)}$ will be called a fundamental solution of (4) if it satisfies the equation

$$
\bar{\delta}_{\xi} \bar{\partial}_{\eta} E^{(h)}=\delta
$$

where $\delta$ is the Dirac distribution.

The following fact is easy to show.

Theorem 3. The distribution

$$
E^{(h)}(\xi, \eta)=h^{2} \sum_{k=0}^{\infty} \sum_{j=0}^{\infty} \delta(\xi-k h, \eta-j h)
$$

is a fundamental solution of (4).
In chapter 6 we will show how fundamental solutions for the operator $\bar{\partial}_{\xi} \bar{\partial}_{\eta}+\lambda^{2}$ can be constructed.

Theorem 4. If $E^{(h)}$ is a fundamental solution of (4) and if the convolution $u^{(h)}=$ $=E^{(h)} * f$ exists, then $u^{(h)}$ is a solution of (4).

Proof. Let the convolution $u * v$ exist. Then $\bar{\partial}_{\xi}\left(u^{*} v\right)=u^{*} \bar{\partial}_{\xi} \nu=\left(\bar{\partial}_{\xi} u\right) * v$. The same equality holds if we replace the differences with respect to $\xi$ by such ones with respect to $\eta$. Therefore,

$$
\bar{\partial}_{\xi} \bar{\partial}_{\eta}\left(E^{(h)} * f\right)=\left(\bar{\partial}_{\xi} \bar{\partial}_{\eta} E^{(h)}\right) * f=f .
$$

If $E^{(h)}$ is the fundamental solution given in Theorem 3 we get

$$
u^{(h)}(\xi, \eta)=\left(E^{(h)} * f\right)(\xi, \eta)=h^{2} \sum_{j=0}^{\infty} \sum_{k=0}^{\infty} f(\xi-k h, \eta-j h) .
$$

Let $\alpha=\alpha(\xi)$ and $\beta=\beta(\eta)$ be two curves in the $(\xi, \eta)$-plane satisfying the condition

$$
\bigwedge_{\nu \in \Gamma} \bigvee_{\mu, \omega \in \Gamma} \alpha(\nu h)=\mu h, \beta(\nu h)=\omega h
$$

and let for fixed $(x, y)$ the region

$$
\Omega_{(x, y)}^{0}=\{(\xi, \eta): \alpha(x)+h / 2<\eta \leqslant y+h / 2, \beta(\eta)+h / 2<\xi \leqslant x+h / 2\}
$$

be not empty. For the sake of simplicity we assume that $(x, y)=(K h, J h)$, where $J$ and $K$ are integers.

To solve our problem we define

$$
\begin{aligned}
& L^{0}=\left\{f \in D^{\prime}\left(R^{2}\right): \operatorname{supp} f \subset \Omega_{(x, y)}^{0}, f \in \mathcal{L}\left(\Omega_{(x, y)}^{0}\right)\right\} \\
& L^{1}=\left\{u \in D^{\prime}\left(R^{2}\right): \operatorname{supp} u \subset \Omega_{(x, y)}^{1}, u \in \mathcal{L}\left(\Omega_{(x, y)}^{1}\right)\right\}
\end{aligned}
$$

where $\Omega_{(x, y)}^{1}=(\xi, \eta): \alpha(x)-h / 2<\eta \leqslant y+h / 2, \beta(\eta)-h / 2<\xi \leqslant x+h / 2$.
Further, Theorem 4 suggests the following definitions:

$$
\begin{equation*}
S: L^{1} \rightarrow L^{0}, S: u \rightarrow\left(\bar{\partial}_{\xi} \bar{\partial}_{\eta} u\right) \mid \Omega_{(x, y)}^{0} \tag{6}
\end{equation*}
$$

$$
T: L^{0} \rightarrow L^{1}, T: f \rightarrow E^{(h)} * f .
$$

For $f \in L^{0}$ we have

$$
S T f=\left(\bar{\partial}_{\xi} \bar{\partial}_{\eta}\left(E^{(h)} * f\right)\right)_{\mid \Omega_{(x, y)}^{0}}^{0}=f_{i} \Omega_{(x, y)}^{0}=f .
$$

Similar like in [3] we derive a fundamental formulae.

- Theorem 5. For $u \in D^{\prime}\left(R^{2}\right) \cap \mathcal{L}\left(\Omega_{(x, y)}^{1}\right)$ the following identity holds:

$$
\begin{equation*}
\Omega_{(x, y)}^{\left\{\int_{\xi}\right.} u \partial_{\xi} \partial_{\eta} \phi d \xi d \eta-\int_{\Omega_{(x, y)} \iint_{\xi} \bar{\partial}_{\eta} u \phi d \xi d \eta=} \tag{7}
\end{equation*}
$$

$$
=-(1 / h) \int_{\alpha(x)+h / 2}^{y+h / 2} \int_{x-h / 2}^{x+h / 2} \phi_{h} \bar{\partial}_{\xi} u d \xi d \eta-(1 / h) \int_{\alpha(x)-h / 2}^{\alpha(x)+h / 2} \int_{\beta(\eta)-h / 2}^{x+h / 2} u \partial_{\xi} \phi d \xi d \eta+
$$

$$
+(1 / h) \int_{y-h / 2}^{y+h / 2} \int_{\beta(\eta)-h / 2}^{x+h / 2} u \partial_{\xi} \phi^{h} d \xi d \eta-(1 / h) \int_{\alpha(x)+h / 2}^{y+h / 2} \int_{\beta(\eta-h)+h / 2}^{\beta(\eta)+h / 2} \phi \bar{\partial}_{\xi} u^{-h} d \xi d \eta+
$$

$$
\left.+(1 / h) \int_{\alpha(x)+h / 2}^{y+h / 2} \beta(\eta)-h / 2\right) \phi \bar{\partial}_{\eta} u d \xi d \eta_{\eta}+
$$

$$
+\left(1 / h^{2}\right) \int_{\alpha(x)+h / 2}^{y+h / 2}\left(\int_{\beta(\eta)-h / 2}^{\beta(\eta)+h / 2} u^{-h} \phi d \xi-\int_{\beta(\eta-h)-h / 2}^{\beta(\eta-h)+h / 2} u^{-h} \phi d \xi\right) d \eta .
$$

By means of distributions (7) reads

$$
\begin{equation*}
\bar{\partial}_{\xi} \bar{\partial}_{\eta} u \mid \Omega_{(x, y)}^{1}-\left(\bar{\partial}_{\xi} \bar{\partial}_{\eta} u\right)_{\mid \Omega_{(x, y)}^{0}}^{0}=V(u), \tag{8}
\end{equation*}
$$

where $V(u)$ is a distribution defined by informations of $u$ on the boundary' of $\Omega_{(x, y)}^{0}$ and given at the right-hand side of (7). If h tends to zero and if $u$ is sufficiently smooth then (7) turns over to the fundamental formulae known from Riemann's method (cf. [3]).

Theorem 6. Each distribution $u \in D^{\prime}\left(R^{2}\right) \cap \mathcal{L}\left(\Omega_{(x, y)}^{\prime}\right)$ can be represented as

$$
\begin{equation*}
u_{\mid} \Omega_{(x, y)}^{1}=E^{(h)} *\left(\left(\bar{\partial}_{\xi} \bar{\delta}_{\eta} u\right)_{\mid} \Omega_{(x, y)}^{0}+V(u)\right) \text {. } \tag{9}
\end{equation*}
$$

where $E^{(h)}$ is the fundamental solution defined in Theorem 3.

Proof. We have

$$
u_{\mid \Omega_{(x, y)}^{\prime}}=\delta^{*} u_{\mid \Omega_{(x, y)}^{\prime}}=\bar{\partial}_{\xi} \bar{\partial}_{\eta} E^{(h)} * u_{i} \Omega_{(x, y)}^{\prime}=E^{(h)} * \bar{\partial}_{\xi} \bar{\partial}_{\eta} u_{\mid \Omega_{(x, y)}^{\prime}} .
$$

Identity (8) finishes the proof.
3. The problem of $\mathbf{Z}$. Szmydt - existence, uniqueness and convergence results. Following Theorem 1 and our definitions (6) we have to define the boundary condition

$$
s u=u-T S u, u \in L^{1}
$$

In view of (9) we get

$$
s u=E^{(h)} * V(u)
$$

The question now is: Which values of $u$ on the ,boun ary" are necessary to describe su at the point $(x, y)$ ? To this aim we assume that there is given a function $\phi \in D\left(R^{2}\right)$ with supp $\phi \subset U(x, y)$, where $U$ is a sufficiently small neighbourhood of $(x, y)$. Via (7) we calculate

$$
\begin{aligned}
& (s u, \phi)=\left(E^{(h)} V(u), \phi\right)= \\
& =\sum_{k=0}^{\infty} \sum_{j=0}^{\infty} \begin{cases}\alpha(x)+h / 2+j h & x+h / 2+k h \\
\int_{\alpha(x)-h / 2+j h} & \int_{\beta(\eta-j h)-h / 2+k h} u_{-k h}^{-j h} \phi d \xi d \eta+\end{cases} \\
& +\int_{\alpha(x)+h / 2+j h} \quad \beta(\eta-j h)-h / 2+k h \int_{-j h}^{-j h} \phi d \xi d \eta- \\
& y+h / 2+j h \quad \beta(\eta-j h)+h / 2+k h \\
& -\int_{\alpha(x)+h / 2+j h} \beta(\eta-h-j h)-h / 2+k h^{-h h} u_{-j h}^{-h} \phi d \xi d \eta- \\
& \begin{array}{ll}
\alpha(x)+h / 2+j h & x+3 h / 2+k h \\
-\int_{\alpha(x)-h / 2+j h} & \beta(\eta-j h)+h / 2+k h
\end{array} u_{-h-k h}^{-j h} \phi d \xi d \eta+
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& K-\beta(\alpha(x)) / h \\
& (s u)(x, y)=(s u)(K h, J h),=\quad \sum_{k=0} \quad u(x-k h, \alpha(x))+ \\
& +\sum_{j=0}^{\delta-1-\alpha(x) / h} u(\beta(y-j h), y-j h)- \\
& -\sum_{j=0}^{J-1-\alpha(x) / h} \quad \begin{array}{ll}
K-\beta(y-j h-h) / h \\
k=K-\beta(y-j h) / h
\end{array} u(x-k h, y-j h-h)- \\
& K-1-\beta(\alpha(x)) / h \\
& \sum_{k=0} \quad u(x-k h-h, \alpha(x))+ \\
& +\sum_{j=0}^{J-1-\alpha(x) / h} \quad k-1-\beta(y-j h-h) / h \quad \sum_{k=K-\beta(y-j h) / h} u(x-k h-h, y-j h-h),
\end{aligned}
$$

that is

$$
\begin{equation*}
(s u)(x, y)=u(x, \alpha(x))+h \sum_{j=0}^{J-1-\alpha(x) / h} \bar{\delta}_{\eta} u(\beta(y-j h), y-j h) . \tag{10}
\end{equation*}
$$

We are able now to formulate the problem of $Z$. Szmydt for the difference equation (4) and give its solution: Find a function $u^{(h)}$ satisfying the functional equation

$$
\begin{equation*}
\bar{\partial}_{\xi} \bar{\partial}_{\eta} u=f(\xi, \eta),(\xi, \eta) \in \Omega, \operatorname{supp} f \subset \Omega \tag{11}
\end{equation*}
$$

and the boundary conditions

$$
u(\xi, \eta)=g_{0}(\xi), \alpha(\xi)-h / 2<\eta<\alpha(\xi)+h / 2
$$

$$
\begin{equation*}
\bar{\partial}_{\eta} u(\xi, \eta)=g_{1}(\eta), \beta(\eta)-h / 2<\xi \leqslant \beta(\eta)+h / 2 . \tag{12}
\end{equation*}
$$

For the sake of simplicity we assume that the given $f_{,} g_{0}$ and $g_{1}$ are at least continuous and that for every point $(\xi, \eta) \in \Omega$ the domain $\Omega_{(\xi, \eta)}^{0}$ is not empty.

Theorem 7. There exists a unique solution of (11), (12). Its values at the gridpoints $(\xi, \eta)=(K h, J h)$ are given by

$$
u^{(h)}(\xi, \eta)=g_{0}(\xi)+h \sum_{j=0}^{J-1-\alpha(\xi) / h} g_{1}(\eta-j h)+
$$

(13)

$$
+h^{2} \sum_{j=0}^{J-1-\alpha(\xi) / h} \quad \sum_{k=0}^{K-1-\beta(\eta-j h) / h} f(\xi-k h, \eta-j h) .
$$

Similar formulae we have for the other points of $\Omega$.
The proof follows immediately from Theorem 1, Chapter 2 and the considerations above.

Like in the "continuous" case we can formulate some other problems resulting from the Z. Szmydt problem, namely
i) the Darboux problem

Here we set $\alpha(\xi)=\eta_{0}=\alpha h, \beta(\eta)=\xi_{0}=\beta h$ and the boundary conditions are

$$
\begin{aligned}
& u(\xi, \eta)=g_{0}(\xi), \eta_{0}-h / 2<\eta \leqslant \eta_{0}+h / 2 \\
& u(\xi, \eta)=g_{1}(\eta), \xi_{0}-h / 2<\xi \leqslant \xi_{0}+h / 2
\end{aligned}
$$

From (10) we calculate

$$
\begin{gathered}
(s u)(\xi, \eta)=u(\xi, \alpha(\xi))+\sum_{f=0}^{J-1-\alpha}(u(\beta h, \eta-j h)-u(\beta h, \eta-j h-h))= \\
=u\left(\xi, \eta_{0}\right)+u\left(\xi_{0}, \eta\right)-u\left(\xi_{0}, \eta_{0}\right) .
\end{gathered}
$$

ii) the Cauchy problem

Let us assume that $\eta=\alpha(\xi) \leftrightharpoons \xi=\beta(\eta)$ ho' 1 d . Then

$$
(s u)(\xi, \eta)=u(\xi, \alpha(\xi))+h \sum_{j=0}^{J-1-\alpha(\xi) / h} \bar{\partial}_{\eta} u\left(\xi_{j}, \alpha(\xi /)\right)
$$

where $\xi_{f}=\beta(\eta-j h)$ and we get the initial conditions

$$
\begin{gathered}
u(\xi, \eta)=g_{0}(\xi), \alpha(\xi)-h / 2<\eta \leqslant \alpha(\xi)+h / 2 \\
\bar{\partial}_{\eta} u(\xi, \eta)=g_{1}(\xi), \alpha(\xi)-h / 2<\eta \leqslant \alpha(\xi)+h / 2 .
\end{gathered}
$$

iii) the Picard problem

We set $\beta(\eta)=0$ and obtain

$$
(s u)(\xi, \eta)=u(\xi, \alpha(\xi))+u(0, \eta)-u(0, \alpha(\xi)),
$$

that means the boundary conditions are

$$
\begin{gathered}
u(\xi, \eta)=g_{0}(\xi), \alpha(\xi)-h / 2<\eta<\alpha(\xi)+h / 2 \\
u(\xi, \eta)=g_{1}(\eta),-h / 2<\xi<h / 2 .
\end{gathered}
$$

In all three cases we can state a result like in Theorem 7.
" If $h$ tends to zero (13) gives the well-known solution formulae of the ,,continuous" problem. The corresponding operators $S, T$ and $s$ are the same like in [6], namely

$$
u(\xi, \eta)=u(\xi, \alpha(\xi))+\int_{\alpha(\xi)}^{\eta} u_{\eta}^{\prime}(\beta(\rho), \rho) d \rho+\int_{\alpha(\xi)}^{\eta} \int_{\beta(\rho)}^{\xi} f(\sigma, \rho) d \sigma d \rho .
$$

The conditions for the curves $\alpha$ and $\beta$ were only restricted by the definition of $\Omega_{(x, y)}^{0}$, where, in addition, we can change the directions of the occuring inequalities. Let us consider an example of an ill-posed problem.

We are looking for a solution of

$$
\begin{align*}
\bar{\partial}_{\xi} \bar{\partial}_{\eta} u & =0  \tag{14}\\
u(\xi, \eta)=g_{0}(\xi),\left(\partial_{\eta} u\right)(\xi, \eta) & =g_{1}(\xi),-h / 2<\eta \leqslant h / 2 \tag{15}
\end{align*}
$$

Solving (14) at the gridpoints we have among others

$$
u(\xi+h, h)=-u(\xi, 0)+u(\xi, h)+u(\xi+h, 0)=h g_{1}(\xi)+g_{0}(\xi+h)
$$

that means we must have $g_{1}(\xi+h)=g_{1}(\xi)$ because of

$$
\begin{aligned}
& g_{1}(\xi+h)=(u(\xi+h, h)-u(\xi+h, 0)) / h= \\
= & \left(h g_{1}(\xi)+g_{0}(\xi+h)-g_{0}(\xi+h)\right) / h=g_{1}(\xi) .
\end{aligned}
$$

Therefore, let $g_{1}$ be a constant. It is easy to verify that

$$
u(\xi, \eta)=F(\xi)+G(\eta)
$$

is a solution of (14) for arbitrary $F$ and $G$. It we set $F(\xi)=g_{0}(\xi)$ we must have $G(0)=0$ and in view of

$$
g_{1}(\xi)=g_{1}=(G(h)-G(0)) / h
$$

we get $G(h)=h g_{1}$. For example, we can set $G(\eta)=g_{1} \eta+H(\eta)$, where $H(0)=H(h)=$ $=0$. Finally, for each function $H$ with $H(0)=(H(0)-H(0)) / h=0$ the function

$$
u(\xi, \eta)=g_{0}(\xi)+g_{1} \eta+H(\eta)
$$

is a solution of (14) satisfying the initial conditions (15). If $h$ tends to zero we arrive at the well-known incorrect problem

$$
u_{\xi \eta}^{\prime \prime}=0, u(\xi, 0)=g_{0}(\xi), u_{\eta}^{\prime}(\xi, 0)=g_{1}
$$

with the solutions

$$
u(\xi, \eta)=g_{0}(\xi)+g_{1} \eta+H(\eta)
$$

where $H$ is an arbitrary function satisfying $H(0)=H^{\prime}(0)=0$.
4. A nonlinear problem. Using explicite finite difference formulae to calculate an approximative solution for the (nonlinear) problem

$$
\begin{gather*}
u_{\xi \eta}^{\prime \prime}=f(u) \\
u(\xi, \alpha(\xi))=g_{0}(\xi)  \tag{16}\\
u_{\eta}^{\prime}(\beta(\eta), \eta)=g_{1}(\eta)
\end{gather*}
$$

we come to

$$
\begin{gather*}
\partial_{\xi} \partial_{\eta} u=f(u),(\xi, \eta) \in \Omega  \tag{17}\\
u(\xi, \eta)=g_{0}(\xi), \alpha(\xi)-h / 2<\eta \leqslant \alpha(\xi)+h / 2
\end{gather*}
$$

$$
\begin{equation*}
\partial_{\eta} u(\xi, \eta)=g_{1}(\eta), \beta(\eta)-h / 2<\xi \leqslant \beta(\eta)+h / 2 \tag{18}
\end{equation*}
$$

Similar like in the preceding chapters we derive a solution formulae, namely

$$
u^{(h)}(\xi, \eta)=g_{0}(\xi)+h \sum_{j=\alpha(\xi) / h}^{J-1} g_{1}(j h)+
$$

(19)

$$
+h^{2} \sum_{j=a(\xi) / h}^{J-1} \sum_{k=\beta(j h) / h}^{K-1} f\left(u^{(h)}(k h, j h)\right),
$$

where $(\xi, \eta)=(K h, J h)$. We note that the solution of (17), (18) exists and is unique if
we demand assumptions about $\alpha$ and $\beta$ closed to that one in Chapter 2 and if $\Omega$ is such a domain that the values of $u^{(h)}$ occuring on the right-hand side of (19) can be obtained from (17) by formulae of type (19). For our further considerations we will identify $\left.u^{( } \boldsymbol{h}\right)$ with the function which arises using linear interpolation over the gridpoint values $u(h)(\xi$, $\eta$ ) given by (19).

Theorem 8. Let $f$ and $g_{1}$ be bounded and continuous, $g_{0}$ and $\alpha$ continuously differentiable. Then the sequence $\left\{u^{(h)}\right\}, h \rightarrow 0$, is compact in the space of continuous functions (with respect to any bounded subset of $\Omega$ ), the limits of the converging subsequences are solutions of (16).

Proof. We have for sufficiently small $h$

$$
\begin{gathered}
\left|u^{(h)}\left(\xi_{1}, \eta_{1}\right)-u^{(h)}\left(\xi_{2}, \eta_{2}\right)\right| \leqslant \\
\leqslant \mid g_{0}\left(x_{1}\right)+h \sum_{j=\alpha\left(x_{1}\right) / h}^{J_{1}-1} g_{1}(j h)+h^{2} \sum_{j=\alpha\left(x_{1}\right) / h}^{J_{1}-1} \sum_{k=\beta(j h) / h}^{K_{1}-1} f\left(u^{(h)}(k h, j h)\right)- \\
-g_{0}\left(x_{2}\right)-h \sum_{j=\alpha\left(x_{2}\right) / h}^{J_{2}-1} g_{1}(j h)-h^{2} \sum_{j=\alpha\left(x_{2}\right) / h}^{J_{2}-1} \sum_{k=\beta(j h) / h}^{K_{2}-1} f\left(u^{(h)}(k h, j h)\right) \mid \leqslant \\
\leqslant C\left(\alpha, \beta, g_{0}, g_{1}, f\right) \max \left(\left|\xi_{1}-\xi_{2}\right|,\left|\eta_{1}-\eta_{2}\right|\right),
\end{gathered}
$$

where $\left(x_{i}, y_{i}\right)=\left(K_{i} h . J_{i} h\right)$ are suitable gridpoints in the neighbourhood of $\left(\xi_{i}, \eta_{i}\right), i=1,2$. Using Arzela's Theorem we have the compactness of our sequence in the maximum-norm, because the $u^{(h)}$ are equi-bounded. Taking a suitable subsequence $h \rightarrow 0$ we obtain

$$
u^{(h)}(\xi, \eta) \rightarrow u(\xi, \eta)=g_{0}(\xi)+\int_{\alpha(\xi)}^{\eta} g_{1}(\sigma) d \sigma+\int_{\alpha(\xi)}^{\eta} \int_{\beta(\sigma)}^{\xi} f(u(\rho, \sigma)) d \rho d \sigma
$$

Of course, $u$ is a solution of (16), moreover, if $f$ is Lipschitz continuous then $u$ is locally unique.

Using fixed-point techniques we can discuss further questions connected with the $\mathbf{Z}$. Szmydt problem for finite differences.
5. Connection with the one-dimensional wave equation. A possible discretization of

$$
\begin{equation*}
\bar{u}_{t t}^{\prime \prime}(x, t)-a^{2} \bar{u}_{x x}^{\prime \prime}(x, t)=\bar{f}(x, t), t>0 \tag{20}
\end{equation*}
$$

may be

$$
\begin{equation*}
(\bar{S} \bar{u})(x, t)=\partial_{t} \bar{\partial}_{t} \bar{u}-a^{2} \partial_{x} \bar{\partial}_{x} \bar{u}=\bar{f}(x, t), t>-\tau / 2, \tag{21}
\end{equation*}
$$

where $\left(\partial_{t} \bar{\partial}_{t} \bar{u}\right)(x, t)=(\bar{u}(x, t+\tau)-2 \bar{u}(x, t)+\bar{u}(x, t-\tau)) / \tau^{2}$ and $\left(\partial_{x} \bar{\partial}_{x} \bar{u}\right)(x, t)=$ $=(\bar{u}(x+h, t)-2 \bar{u}(x, t)+\bar{u}(x-h, t)) / h^{2}$.

We will assume that $h=a \tau$. To construct suitable initial conditions for (21) we define the isomorphic mappings $\psi_{0}, \psi_{1}$ acting as follows:

$$
\begin{gathered}
f(\xi, \eta)=\left(\psi_{0}^{-1} \bar{f}\right)(\xi, \eta)=\bar{f}((\eta-\xi) / 2,(\eta+\xi) / 2 a), \\
\bar{f}(x, t)=\left(\psi_{0} f\right)(x, t)=f(-x+a t, x+a t)
\end{gathered}
$$

and

$$
\begin{aligned}
& \left.u(\xi, \eta)=\left(\psi_{1}^{-1} \bar{u}\right)(\xi, \eta)=4 a^{2} \bar{u}((\eta-\xi) / 2,(\eta+\xi) / 2 a+\tau)\right), \\
& \bar{u}(x, t)=\left(\psi_{1} u\right)(x, t)=\left(1 / 4 a^{2}\right) u(-x+a t-h, x+a t-h) .
\end{aligned}
$$

From Definition 2 we have for the equivalent derivative with respect to $\psi_{0}, \psi_{1}$

$$
S=\psi_{1} \bar{S} \psi_{0}^{1}
$$

and therefore (by suitable calculations)

$$
(S u)(\xi, \eta)=\bar{\delta}_{\xi} \bar{\delta}_{\eta} u(\xi, \eta)
$$

where the stepsize here is $2 h$. We define the curves $\alpha(\xi)=-\xi-2 h$ and $\beta(\eta)=-\eta-2 h$. Knowing the integral $T$ of $S$ given by (6) and (13) at the gridpoints, namely

$$
(T f)(\xi, \eta)=(2 h)^{2} \sum_{j=0}^{(\xi+\eta) / 2 h} \quad \sum_{k=0}^{(\xi+\eta) / 2 h-1-j} f(\xi-k h, \eta-j h)
$$

we obtain the integral $\bar{T}$ of $\bar{S}$ according to

$$
\begin{gathered}
(\bar{T} \bar{f})(x, t)=\left(\psi_{1} T \psi_{0}^{-1} \bar{f}\right)(x, t)= \\
=\tau^{2} \sum_{f=0}^{\bar{f}=1} \sum_{k=0}^{t / r-1-f} f(x-j h+k h, t-(j+1) \tau-k \tau)
\end{gathered}
$$

and changing the summation

$$
\begin{equation*}
(\bar{T} \bar{\jmath})(x, t)=(h \tau) / a \sum_{\sigma=0}^{t / \tau-1} \sum \bar{f}(\rho h, \sigma \tau), \tag{22}
\end{equation*}
$$

where $\rho$ steps with stepsize 2 from $x / h-t / \tau+\sigma+1$ to $x / h+t / \tau-\sigma-1$. Here we took into consideration that $(x, t)$ is a gridpoint iff $(\xi, \eta)$ is a gridpoint.

If $h=a \tau$ tends to zero we have

$$
(\bar{T} \bar{f})(x, t) \rightarrow(1 / 2 a) \int_{0}^{t} \int_{x-a t+a \sigma}^{x+a t-a \sigma} \bar{f}(\rho, \sigma) d \rho d \sigma .
$$

For sufficiently smooth $\bar{f}$ the integral on the right-hand side is a solution of (20).
To construct the boundary conditions for $\bar{S}, \bar{T}$ we use

$$
(s u)(\xi, \eta)=u(\xi,-\xi-2 h)+2 h \sum_{j=0}^{(\xi+\eta) / 2 h}\left(\bar{\partial}_{\eta} u\right)(-\eta+2(j-1) h, \eta-2 j h)
$$

given by (10). Elementary calculations show that

$$
\begin{equation*}
(\bar{s} \bar{u})(x, t)=\bar{u}(x-a t, 0)+h \sum_{\rho}\left(\partial_{x} \bar{u}\right)(\rho h, 0)+\sum_{\rho}\left(\bar{\partial}_{t} \bar{u}\right)(\rho h, 0), \tag{24}
\end{equation*}
$$

where $\rho$ steps with stepsize 2 from $x / h-t / \tau+1$ to $x / h+t / \tau-1$. If $h$ tends to zero we get now

$$
\begin{equation*}
(\bar{s} \bar{u})(x, t) \rightarrow \bar{u}(x-a t, 0)+1 / 2 \int_{x-a t}^{x+a t} \bar{u}_{x}^{\prime}(\rho, 0) d \rho+1 / 2 a \int_{x-a t}^{x+a t} \bar{u}_{t}^{\prime}(\rho, 0) d \rho= \tag{25}
\end{equation*}
$$

$$
=(\bar{u}(x+a t, 0)+\bar{u}(x-a t, 0)) / 2+1 / 2 a \int_{x-a t}^{x+a t} \bar{u}_{t}^{\prime}(\rho, 0) d \rho .
$$

The last term is a solution of the homogenous equation (20). if the corresponding derivatives exist.

Collecting the preceding results we have proved the following statement (cf. [1]).
Theorem 9. Equation (21) possesses in connection with the initial conditions

$$
\begin{gathered}
\bar{u}(x, t)=\bar{g}_{0}(x),-\tau / 2<t \leqslant \tau / 2 \\
\bar{\partial}_{i} \bar{u}(x, t)=\bar{g}_{1}(x),-\tau / 2<t \leqslant \tau / 2
\end{gathered}
$$

a unique solution $\bar{u}^{(h)}, h=a \tau$, gisen at the gridpoints by (22), (24) and

$$
\bar{u}^{(h)}(x, t)=\left(\bar{s} \bar{u}^{(h)}\right)(x, t)+(\bar{T} \bar{f})(x, t) .
$$

If $h$ approaches zero the sequence $\bar{u}^{(\hat{h})}(x, t)$ conterges for each $(x, t)$ to the solution of (20) given by (23), (25) with the initial conditions

$$
\begin{aligned}
\bar{u}(x, 0) & =\bar{g}_{0}(x) \\
\bar{u}_{i}^{\prime}(x, 0) & =\bar{g}_{1}(x),
\end{aligned}
$$

if the right-hand sides $\bar{f}_{1} \bar{g}_{0}$ and $\bar{g}_{1}$ are sufficiently smooth (cf. [3]).
6. The construction of fundamental solutions for $\bar{\partial}_{\xi} \bar{\partial}_{\eta}+\lambda^{2}$. In connection with $D_{\text {s }}$ finition 3 we are looking for a solution $E^{(h)}$ satisfying

$$
\begin{equation*}
\bar{\partial}_{\xi} \bar{\partial}_{\eta} E^{(h)}+\lambda^{2} E^{(h)}=\delta . \tag{26}
\end{equation*}
$$

Applying the Fourier transformation given by the formulae (cf. [2])

$$
\begin{gathered}
\left(F E^{(h)}, F \phi\right)=(2 \pi)^{2}\left(E^{(h)}, \phi\right) \\
(F \phi)(s, t)=\iint_{R^{2}} e^{l(s \xi+t \eta)} \phi(\xi, \eta) d \xi d \eta, \phi \in D\left(R^{2}\right)
\end{gathered}
$$

on both sides of (26) we obtain the problem

$$
\begin{equation*}
P^{(h)}(s, t) F E^{(h)}=1 \tag{27}
\end{equation*}
$$

where

$$
P^{(h)}(s, t)=\frac{\left(1-e^{i h s}\right)\left(1-e^{i h t}\right)}{h^{2}}+\lambda^{2}
$$

Equation (27) possesses the formal solution $F E^{(h)}=1 / P^{(h)}$. Because $P^{(h)}$ vahishes for certain $s, t$ we have to interpret $1 ; P(h)$ in a suitable way. We will do this in an analoguous manner like in [9], the main idea can be found for example in [4], where fundamental solutions for differential operators are constructed.

We assume for a moment that $\lambda$ is a positive real number.
Theorem 10. The distribution FE( $h$ ) defined by

$$
\begin{equation*}
\left(F E^{(h)}, F \phi\right)=\iint_{R^{2}} \frac{(F \phi)(s+i \sigma, t+i \sigma)}{P^{(h)}(s+i \sigma, t+i \sigma)} d s d t \tag{28}
\end{equation*}
$$

with $\sigma=\sigma(h)$ from $e^{\sigma h}=1+N_{1}$, is a solution of (27) and, therefore, $E^{(h)}$ is a solution of (26). If $h$ tends to zero $E^{(h)}$ converges to a fundamental solution $E$ of the corresponding differential operator $\partial^{2} / \partial_{\xi} \partial_{\eta}+\lambda^{2}$.

Proof. By suitable calculations we obtain

$$
\left|P^{(h)}(s+i 0, t+i \sigma)\right|=\left|\frac{\left(1+\lambda h-e^{i h s}\right)\left(1+\lambda t-e^{i h t}\right)}{(1+\lambda t)^{2} h^{2}}+\lambda^{2}\right| \geqslant \lambda^{2}\left(1+\frac{1}{(1+\lambda h)^{2}}\right)
$$

that means, (28) defines a distribution acting on $F \phi$. Because $P^{(h)}(s+i \sigma, t+i \sigma)$ tends to $P(s+i \lambda t+i \lambda)=-(s+i \lambda)(t+i \lambda)+\lambda^{2}$ if $h$ approaches zero we can use Lebesgue's Theorem get

$$
\left(F E^{(h)}, F \phi\right) \rightarrow \iint_{R^{2}} \frac{(F \phi)(s+i \lambda, t+i \lambda)}{P(s+i \lambda, t+i \lambda)} d s d t \stackrel{\text { def }}{=}(F E, F \phi)
$$

In view of the continuity of the inverse Fourier transformation we have $E^{(h)} \rightarrow E$. Further,

$$
\left(P^{(h)} F E^{(h)}, F \phi\right)=\left(F E^{(h)}, P^{(h)} F \phi\right)=\iint_{R^{2}}(F \phi)(s+i \sigma, t+i \sigma) d s d t=(1, F \phi)
$$

that is (27). Similar considerations show that the distribution $F E$ satisfies ( - is) ( - it) $F E+\lambda^{2} F E=1$. Therefore, $E(h)$ and $E$ are the desired fundamental solutions.

Theorem 13. The fundamental solution $E^{(h)}$ given in (28) has the form

$$
E^{(h)}(\xi, \eta)=\sum_{k=0}^{\infty} \sum_{j=0}^{\infty} c_{k j} \delta(\xi-k h, \eta-j h)
$$

where

$$
\begin{equation*}
c_{k j}=h^{2} \sum_{m=0}^{k}\left(\frac{f}{m}\right)\binom{k}{m}(-1)^{m}(\lambda h)^{2 m}\left(1+\lambda^{2} h^{2}\right)^{-1-k-1} \tag{29}
\end{equation*}
$$

If $h \rightarrow 0$ we have

$$
E^{(h)}(\xi, \eta) \rightarrow E(\xi, \eta)=\sum_{m=0}^{\infty} 1 /(m!)^{2}(-1)^{m}\left(\lambda^{2} \xi \eta\right)^{m} Y(\xi) \otimes Y(\eta)
$$

( $Y$ is the Heaviside unit function). $E$ is the fundamental solution found in [8].
Proof. Formulac (28) shows that $F E^{(h)}$ is a periodic distribution with period $T=$ $=(2 \pi / h, 2 \pi / h)$. That means (cf. [7]) that

$$
E^{(h)}(\xi, \eta)=\sum_{k=-\infty}^{\infty} \sum_{j=-\infty}^{\infty} c_{k j} \delta(\xi-k h, \eta-j h)
$$

where the $c_{k}$ are the generalized Fourier coefficients of $1 / P^{(h)}$ given by

$$
c_{k j}=\frac{h^{2}}{(2 \pi)^{2}} \int_{0}^{2 \pi / h} \int_{0}^{2 \pi / h} \frac{e^{-i k h(s+i \sigma)} e^{-i j h(t+i \sigma)}}{P(h)(s+i \sigma, t+i \sigma)} d s d t .
$$

The substitution $u=e^{-i h(s+i \sigma)}, v=e^{-i h(t+i \sigma)}$ leads to

$$
c_{k j}=\frac{h^{2}}{(2 \pi i)^{2}} \oint_{|v|=e^{h o}}^{h_{0}} \oint_{|u|=e^{h}} \frac{u^{k} v^{\prime}}{\left(u-u_{0}(v)\right)\left(v-v_{0}\right)\left(1+\lambda^{2} h^{2}\right)} d u d v
$$

with $u_{0}(v)=\frac{v-1}{v\left(1+\lambda^{2} h^{2}\right)-1}$ and $v_{0}=\frac{1}{1+\lambda^{2} h^{2}}$. If $|v|=e^{o h}=1+\lambda h$, then

$$
\begin{equation*}
\left|u_{0}(v)\right| \leqslant 1+\frac{\lambda^{2} h^{2}|v|}{|v|\left(1+\lambda^{2} h^{2}\right)-1}<1+\lambda h=e^{o h} . \tag{30}
\end{equation*}
$$

In accordance to (30) we calculate for $k \geqslant 0$ and $j \geqslant 0$

$$
\begin{gathered}
c_{k j}=\frac{h^{2}}{2 \pi i} \oint_{|\nu|=e^{\sigma h}} \frac{v^{j}(v-1)^{k}}{\left(v-v_{0}\right)^{k+1}\left(1+\lambda^{2} h^{2}\right)^{k+1}} d v= \\
=h^{2} \frac{1}{k!} \frac{1}{\left(1+\lambda^{2} h^{2}\right)^{k+1}} \sum_{m=0}^{k}\binom{k}{m} \frac{d^{m}}{d v^{m}} \nu^{j} / v=v_{0} \frac{d^{k-m}}{d v^{k-m}}(v-1)^{k / v=v_{0}} .
\end{gathered}
$$

This is already (29) because $c_{k j}=c_{j k}$ and

$$
\begin{array}{r}
c_{k \mid}=\frac{h^{2}}{2 \pi i} \oint_{|v|=e^{\sigma h}} \frac{v^{f}}{\left(v-v_{0}\right)\left(1+\lambda^{2} h^{2}\right)}\left(\frac{1}{(-k-1)!} \frac{d^{-k-1}}{d u^{-k-1}}\left(\frac{1}{u-u_{0}(v)}\right)_{i u=u_{b}^{+}}+\right. \\
\left.+\left(u_{0}(v)\right)^{k}\right) d v=0
\end{array}
$$

for $k<0$.
To show the covergence of $E^{(h)}$ to $E$ we pay attention to

$$
\left(E^{(h)}, \phi\right)=\sum_{k=0}^{\infty} \sum_{j=0}^{\infty} c_{k /} \phi(k h, j h) \rightarrow \iint_{R^{2}} E \phi d \xi d \eta=(E, \phi) .
$$

We notice that (29) defines a fundamental solution of $\bar{\delta}_{\xi} \bar{\partial}_{\eta}+\lambda^{2}$ for every complex number $\lambda$ such that $1+\lambda^{2} h^{2}$ does not vanish.

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## STRESZCZENIE

W pracy tej znajduje się przyblizone rozwiązanie problemu Z. Szmydt przy pomocy równań rózznicowych. W' tym celu stosuje się formalizm użyty w monografii Bittnera [6]. Jest to dalszy przykład anaiugii pomiędzy równaniami różnicowymi i różniczkowymi.

## PЕЗЮME

В этой работе дается приближенное решение задачи С. 山мыдт при использованни разностных уравнения. Для этой цели использован формализм из монографии Р. Биттнера [6]. Это служит очередным примером аналогии между разностными и дифференииальными уравнениями.

