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*n***-Geodesics on Hypersurfaces**

л-geodezyjne na hiperpowierzchniachл-геодезические на хиперповерхностях

In this paper we deal with the problem of the coincidence of π -geodesics with geodesics on a hypersurface $\mathbb{M}^n \subset \mathbb{E}^{n+1}$. In the first part of this paper we'll consider those π -geodesics which are determined by a tensor \mathcal{T} of the type (0,2) that is associated in a natural way with hypersurfaces e.g. the third and fourth fundamental tensors of hypersurfaces. In the second part we define π -geodesics determined by a tensor field π of the type (1,1).

1. T-GEODESICS WITH T BEING OF THE TYPE (0,2).

First we recall some fundamental definitions and theorems.

DEFINITION 1 [8]. A vector field \overline{w} on a manifold M with a given linear connection Γ is said to be π -geodesic if:

$$\nabla_{\overline{w}} \pi^{\overline{w}} = \lambda \pi^{\overline{w}}; \qquad \pi^{\overline{w}}: \overline{v} \longmapsto \pi(\overline{v}, \overline{w})$$

where π is a symmetric, non-singular tensor field on M of the type (0,2) and λ is a real differentiable function on M. The integral curve of the π -geodesic vector field on M is called the π -geodesic line.

In a local map U, the equation of this line is:

(1)
$$\frac{d^2u^1}{dt^2} + \left(\int_{ks}^1 + \widetilde{\pi}^{1p} \nabla_k \pi_{ps} \right) \frac{du^k}{dt} \frac{du^s}{dt} = \lambda \frac{du^1}{dt}$$

THEOREM 1 [6], [7]. The necessary and sufficient condition for π -geodesics on a manifold M to coincide with geodesics of the connection $\lceil \rceil$ is:

(2)
$$\nabla_k \pi_{ij} + \nabla_i \pi_{kj} = p_k \pi_{ij} + p_i \pi_{kj}$$

In particular, if T is symmetric, then (2) becomes:

(3)
$$\nabla_k \pi_{ij} = p_k \pi_{ij}$$

where pk is some covector field on M.

THEOREM 2 [3]. If, on a surface $M^2 \subset E^3$ with $K \neq 0$, symmetric tensor fields g and \hat{g} are the solutions of the equation: $\nabla_k \epsilon_{ij} = 0$ and $\det(g_{ij}) \neq 0$, $\det(\hat{g}_{ij}) \neq 0$, then $\hat{g} = \alpha g$, $\alpha = \text{const.}$ (∇ - the Levi-Civita connection).

DEFINITION 2 [5]. Let ∇ be an n-dimensional vector space and $R \in Hom(\nabla \wedge \nabla, Hom(\nabla, \nabla))$. The mapping R is said to be regular if and only if $R(X \wedge Y) \neq 0$ for each bivector $X \wedge Y \in \nabla \wedge \nabla = \{0\}$.

π-Geodesics on Rypersurfaces

DEFINITION 3. A point $x \in M$ is said to be regular for the curvature tensor R of a differentiable manifold $\cdot M$ with a linear connection Γ if

R E Hom(T, M AT, M, Hom(T, M, T, M))

is a regular mapping.

We have:

THEOREM 3 [5]. Suppose, that two Riemannian connections given on a connected differentiable manifold M of dimension $n \ge 3$ with metric tensors g and \hat{g} , have the same curvature tensors and the set of regular points of these tensors is dense in M. Then $\hat{g} = \lambda g$ where $\lambda = \text{const.}$

REMARK 1. Observe, that in case of a surface $M^2 \subset E^3$, the dimension of $T_x M^2 \wedge T_x M^2$ is one and the condition of regularity of the curvature tensor R of the Levi-Civita connection of M^2 at any x is equivalent to the non-vanishing of the Gaussian curvature of M^2 at this point, namely: if S_{1j} and b_{1j} are components of the first and the second fundamental tensors of M^2 respectively, then:

$$R_{jklp} = R_{jkl}^{1} S_{ip} = b_{jp} b_{kl} - b_{kp} b_{jl}$$

or

$$R_{jkl}^{1} = (b_{jp}b_{kl} - b_{kp}b_{jl})g^{p1}$$

and if \overline{x}_1 , \overline{x}_2 are vectors of the natural basis of $T_{\chi}M^2$, then:

$$R(\bar{x}_1 \wedge \bar{x}_2) = (b_{11}b_{2k} - b_{21}b_{1k})g^{r1}$$

Since det(g^{ri}) $\neq 0$, then $\mathbb{R}(\overline{x}_1 \wedge \overline{x}_2) = 0$ if and only if:

 $b_{11}b_{2k} - b_{21}b_{1k} = 0$ for each i,k = 1,2, what is equivalent to det(b_{1j}) = 0. And so $R(\overline{x}_1 \wedge \overline{x}_2) \neq 0$ is equivalent to $K \neq 0$.

When we combine theorems 2 and 3 we get:

THEOREM 4. If Γ is the Levi-Civita connection of a hypersurface $\mathbb{M}^n \subset \mathbb{E}^{n+1}$, $n \ge 2$ such, that the set of regular points of the curvature tensor R is dense in \mathbb{M}^n and g, \hat{g} are symmetric, non-singular tensors with $\nabla_i g_{jk} = \nabla_i \hat{g}_{jk} = 0$ then $\hat{g}_{ij} = \lambda g_{ij}$ with $\lambda = \text{const.}$

Now we can prove two more theorems:

THEOREM 5. Suppose, that on a Riemannian manifold M with the metric tensor g, there is given a non-singular, symmetric tensor field π of the type (0,2) satisfying $\pi_{ij}g^{ij} \neq 0$ everywhere on M. Then, if π -geodesics coincide with geodesics on M, we have: $\nabla_k \pi_{ij} = p_k \pi_{ij}$ and $p_k = \partial_k \ln |\pi^g|$ where $\pi^g = \pi_{ij}g^{ij}$ and there exists a scalar function $\lambda \neq 0$ such, that $\nabla_k(\lambda \pi_{ij}) = 0$ and $\lambda = c(\pi^g)^{-1}$, $c = const \neq 0$.

Proof. Since T-geodesics are geodesics on M, thus:

$$\nabla_k \pi_{ij} = P_k \pi_{ij}$$

In virtue of the fact that $\nabla_{ir} g^{js} = 0$ we have:

$$\nabla_{\mathbf{k}}(\pi_{\mathbf{ij}}\mathbf{g}^{\mathbf{js}}) = \mathbf{p}_{\mathbf{k}}\pi_{\mathbf{ij}}\mathbf{g}^{\mathbf{js}}$$

Putting s = i and summing with respect to i, we get:

$$\nabla_k \pi^g = p_k \pi^g$$

or

Hence

$$a_{\rm L} = \partial_{\rm L} \ln |\pi^{\rm S}|$$

Now, let $\hat{\pi} = \lambda \pi$, $\lambda \neq 0$ and $\nabla \hat{\pi} = 0$, then:

$$\nabla_{k} \hat{\pi}_{ij} = \partial_{k} \lambda \pi_{ij} + \lambda \nabla_{k} \pi_{ij} = \partial_{k} \lambda \pi_{ij} + \lambda p_{k} \pi_{ij} =$$
$$= \partial_{k} \lambda \pi_{ij} + \lambda \partial_{k} \ln |\pi^{g}| \pi_{ij} = 0$$

Hence

$$\partial_k \lambda + \lambda \partial_k \ln |\pi^{\mathsf{g}}| = 0$$

Or

$$\partial_{\mu} \ln \left| \lambda \pi^{g} \right| = 0$$

or

$$\lambda = c(\pi^{g})^{-1} \qquad Q.E.D.$$

THEOREM 6. Suppose that two Riemannian connections Γ and $\hat{\Gamma}$ are given on a differentiable, connected manifold M with the metric tensors g and \hat{g} , respectively. Assume that the set of regular points of the curvature tensor R of the connection Γ is dense in M and $\nabla_i \hat{e}_{kj} = \nabla_k \hat{e}_{ij}$, where ∇ is a differentiation operator with respect to Γ . Then Γ and $\hat{\Gamma}$ have the same geodesics if and only if $\hat{\varepsilon} = \lambda g$ with $\lambda = \text{const.}$

Proof. From the condition (11) [8] we know that Γ and $\hat{\Gamma}$ determine the same family of geodesics if and only if:

$$\Gamma_{jk}^{i} = \Gamma_{jk}^{i} + P_{j} \delta_{k}^{i} + P_{k} \delta_{j}^{i}$$

Now we can find: Vigkr:

$$\nabla_{j}\hat{g}_{kr} = \hat{\nabla}_{j}\hat{g}_{kr} - (p_{j}\delta_{k}^{1} + p_{k}\delta_{j}^{1})\hat{g}_{ir} - (p_{j}\delta_{r}^{1} + p_{r}\delta_{j}^{1})\hat{g}_{ik}^{=}$$
$$= -(2p_{j}\hat{g}_{kr} + p_{k}\hat{g}_{jr} + p_{r}\hat{g}_{jk})$$

Since $\nabla_j \hat{g}_{kr} = \nabla_k \hat{g}_{jr}$, so we have:

$$2p_j\hat{e}_{kr} + p_k\hat{e}_{jr} + p_r\hat{e}_{jk} = 2p_k\hat{e}_{jr} + p_j\hat{e}_{kr} + p_r\hat{e}_{jk}$$

or

or

$$p_j \delta_k^s = p_k \delta_j^s$$

Piekr = Preir

Putting s = k and summing over k, we get:

$$p_{j} = 0$$

$$\neg_{ik} = \bigcap_{ik}^{i}$$

Hence

$$\lambda_{ij} = \lambda_{g_{ij}}, \quad \lambda = \text{const.} \quad Q.E.D.$$

The following will be useful:

THEOREM 7 [6]. Suppose, that $\[Gamma]$ is a symmetric, linear connection on M with the symmetric Ricci tensor \Re . If π is a non-singular tensor field of the type (0,2) and $\nabla_k \pi_{ij} = p_k \pi_{ij}$ where p is a covector field on M, then p is the gradient field (i.e. $p_k = \partial_k f$, where f is a scalar function on M).

REMARK 2. If the assumptions of this theorem hold, then one can find a scalar function $\lambda \neq 0$ such that

X-Geodesics on Hypersurfaces

 $\nabla_{\mu}(\lambda \pi_{1}) = 0$ (compare the proof of the theorem 5).

At last, we deal with π -geodesics in case π is a tensor field associated in a natural way with a hypersurface $\mathbb{M}^n \subset \mathbb{E}^{n+1}$ i.e. π is either the third, or the fourth fundamental tensor of a hypersurface.

In the paper [2] the following has been proved:

THEOREM 8 [2]. Let $M^2 \subset E^3$ be a surface and $K \neq 0$ being its Gaussian curvature. The family of b-geodesics on M^2 coincides with the family of geodesics of this surface if and only if K = const and H = const, where b is the second fundamental tensor of M^2 . We can prove:

THEOREM 9. On a surface $M^2 \subset E^3$ with the gaussian curvature $K \neq 0$ h-geodesics, where $h_{ij} = \alpha b_{ij} + \beta E_{ij}$, $\alpha \neq 0$, $det(h_{ij}) \neq 0$, coincide with geodesics of this surface if and only if M^2 is a sphere (locally).

Proof.

 \Rightarrow On account of the Theorem 7 and the Remark 2, we have:

$$V_k(\lambda h_{ij}) = 0$$

From the Theorem 2, we get:

$$\lambda h_{ij} = \mu g_{ij}$$

'or

We now show that γ is constant. From the above equality we get:

Having used the Codazzi equations for bii, we obtain:

$$0 = \nabla_{\mathbf{k}} \mathbf{b}_{\mathbf{ij}} - \nabla_{\mathbf{i}} \mathbf{b}_{\mathbf{kj}} = \partial_{\mathbf{k}} \gamma \mathbf{e}_{\mathbf{ij}} - \partial_{\mathbf{i}} \gamma \mathbf{e}_{\mathbf{kj}}$$

or

$$\partial_k \gamma \delta_i^s - \partial_i \gamma_k^s = 0$$

Putting s = i, we get:

$$\partial_{\nu} \gamma(n-1) = 0$$

and $\gamma = const$ for n > 1.

< It is obvious.

Q.E.D.

DEFINITION 4 [4]. Let $M^n \subset E^{n+1}$ be an orientable hypersurface and N denote the normal vector field to M^n , then a tensor field c of the type (0,2) on M^n defined in the following way:

$$c(X,Y) = (dN)(X) \cdot (dN)(Y)$$

is said to be the third fundamental tensor of Mⁿ.

If g_{ij} and b_{ij} are the components of the first and the second fundamental tensors of M^n respectively, then:

(4)
$$c_{ij} = b_{is} \tilde{g}^{st} b_{tj}$$

are the components of the third fundamental tensor of M^n . In particular, for n = 2:

$$c_{ij} = 2Hb_{ij} - Kg_{ij}$$

where K and H are the Gaussian and the mean curvatures of M² respectively.

Now, if we take $\alpha = 2H$ and $\beta = -K$ in the Theorem 9, we'll get:

X-Geodesics on Hypersurfaces

THEOREM 10. On a surface $M^2 \subset E^3$ with $K \neq 0$ and $H \neq 0$, c-geodesics coincide with geodesics on M^2 if and only if H = const and K = const or M^2 is a sphere (locally).

For n>2 we have:

THEOREM 11. Suppose that the set of regular points of the curvature tensor R of the Levi-Civita connection Γ on a hypersurface $M^n \subset E^{n+1}$, $n \ge 3$ is dense in M^n and det(b₁₁) $\neq 0$ and

(6)
$$b_{ij}b_{km}\tilde{g}^{jk}\tilde{g}^{mi} = \text{const} \neq 0$$

Then, c-geodesics coincide with geodesics on Mⁿ if and only if Mⁿ is a sphere (locally).

Proof. Suppose, that c-geodesics coincide with geodesics on M^n . Then, from the Theorem 1, we have:

 $\nabla_{\mathbf{k}} \mathbf{c}_{\mathbf{ij}} = \mathbf{p}_{\mathbf{k}} \mathbf{c}_{\mathbf{ij}}.$

that:

By virtue of the condition (6) and the Theorem 5 there exists $\lambda = \mu(c^g)^{-1} = \text{const}, c^g = b_{is} \tilde{c}^{st} b_{ti} \tilde{c}^{j1}, \mu = \text{const}$ such,

(7)
$$V_{\mathbf{k}}(\lambda \mathbf{c}_{\mathbf{i}\mathbf{j}}) = 0$$

From the Theorem 4 it follows that:

(8)
$$o_{ij} = \alpha g_{ij}, \quad \alpha = \text{const}$$

After having multiplied (8) by g^{jk} and having substituted c_{ij} from (4), we get:

(9)
$$b_{ik}\tilde{g}^{kl}b_{lj}\tilde{g}^{jr} = \alpha \delta_{1}^{r}$$

Because of (9), the tensor:

(10)
$$h_j^i = b_{js}g^{si}$$
 $(\tilde{h}_p^j = \tilde{b}^{jr}g_{rp})$

satisfies the condition (2) of the Theorem 2 [1], i.e.

$$\nabla_{\mathbf{s}}(\mathbf{h}_{\mathbf{p}}^{\mathbf{j}}\mathbf{h}_{\mathbf{j}}^{\mathbf{1}}) = 0$$

so it says, that there exists the connection $\widetilde{\Gamma}$ such, that:

(11)
$$\tilde{\nabla}_{\mathbf{s}}\mathbf{h}_{\mathbf{j}}^{\mathbf{j}} = 0$$

where $\widetilde{\Gamma}_{jk}^{i} = \Gamma_{jk}^{i} + \frac{1}{2} \widetilde{h}_{p}^{i} \nabla_{j} h_{k}^{p} = \Gamma_{jk}^{i} + \frac{1}{2} \widetilde{b}^{ir} \varepsilon_{rp} \nabla_{j} (b_{ks} \widetilde{\varepsilon}^{sp}) =$ = $\Gamma_{jk}^{i} + \frac{1}{2} \widetilde{b}^{ir} \varepsilon_{rp} \widetilde{\varepsilon}^{sp} \nabla_{j} b_{ks} = \Gamma_{jk}^{i} + \frac{1}{2} \widetilde{b}^{ir} \nabla_{j} b_{kr}$

we now compute Vabik:

$$\widetilde{\nabla}_{\mathbf{s}} \mathbf{b}_{\mathbf{j}\mathbf{k}} = \partial_{\mathbf{s}} \mathbf{b}_{\mathbf{j}\mathbf{k}} - \widetilde{\Gamma}_{\mathbf{s}\mathbf{j}}^{\mathbf{p}} \mathbf{b}_{\mathbf{p}\mathbf{k}} - \widetilde{\Gamma}_{\mathbf{s}\mathbf{k}}^{\mathbf{p}} \mathbf{b}_{\mathbf{j}\mathbf{p}} = \nabla_{\mathbf{s}} \mathbf{b}_{\mathbf{j}\mathbf{k}} - \frac{1}{2} \widetilde{\mathbf{b}}^{\mathbf{p}\mathbf{r}} \nabla_{\mathbf{s}} \mathbf{b}_{\mathbf{j}\mathbf{p}} \nabla_{\mathbf{s}} \mathbf{b}_{\mathbf{k}\mathbf{r}} = \nabla_{\mathbf{s}} \mathbf{b}_{\mathbf{j}\mathbf{k}} - \frac{1}{2} \widetilde{\nabla}_{\mathbf{s}} \mathbf{b}_{\mathbf{j}\mathbf{p}} \nabla_{\mathbf{s}} \mathbf{b}_{\mathbf{k}\mathbf{r}} = \nabla_{\mathbf{s}} \mathbf{b}_{\mathbf{j}\mathbf{k}} - \frac{1}{2} \nabla_{\mathbf{s}} \mathbf{b}_{\mathbf{j}\mathbf{k}} - \frac{1}{2} \nabla_{\mathbf{s}} \mathbf{b}_{\mathbf{k}\mathbf{j}} = 0$$

Using (11) and (12), we have:

$$0 = \widetilde{\nabla}_{g}h_{j}^{i} = \widetilde{\nabla}_{g}(b_{jk}\widetilde{g}^{ki}) = \widetilde{g}^{ki}\widetilde{\nabla}_{g}b_{jk} + b_{jk}\widetilde{\nabla}_{g}\widetilde{g}^{ki} = b_{jk}\widetilde{\nabla}_{g}\widetilde{g}^{ki}$$

Hence $\tilde{\nabla}_{g}\tilde{g}^{ki} = 0$

or

(13)
$$\widetilde{\nabla}_{s} \mathbf{g}_{jk} = 0$$

It is easy to observe, that $\tilde{\Gamma}$ is torsionless (we use the Codazzi equations for b_{ij}), so we can apply the Theorem 3 and as a result we have: $b_{ij} = \gamma \varepsilon_{ij}$, $\gamma = \text{const.}$ Q.E.D.

X-Geodesics on Hypersurfaces

DEFINITION 5 [4]. A tensor field ρ on a hypersurface $\mathbb{M}^n \mathbb{C} \mathbb{E}^{n+1}$ with the components:

(14)
$$\rho_{ij} = \frac{1}{2} (\varepsilon_{ik} h_j^k + \varepsilon_{jk} h_i^k)$$

where $h_{i}^{k} = b_{ip} \tilde{g}^{pk}$ and $\mathcal{E}_{ij} = \begin{cases} \sqrt{g} & \text{if } i < j \\ -\sqrt{g} & \text{if } i > j, \\ 0 & \text{if } i = j \end{cases}$ is said to be the fourth fundamental tensor of $M^{n} \subset \mathbb{R}^{n+1}$. Now, let n = 2, then:

$$\begin{aligned} \rho_{11} &= \frac{1}{2} \left(e_{1k} h_{1}^{k} + e_{1k} h_{1}^{k} \right) = e_{12} h_{1}^{2} = \sqrt{8} h_{1}^{2} \\ \rho_{12} &= \frac{1}{2} \left(e_{1k} h_{2}^{k} + e_{2k} h_{1}^{k} \right) = \frac{1}{2} \left(e_{12} h_{2}^{2} + e_{21} h_{1}^{1} \right) = \\ &= \frac{1}{2} \sqrt{8} \left(h_{2}^{2} - h_{1}^{1} \right) \\ \rho_{22} &= \frac{1}{2} \left(e_{2k} h_{2}^{k} + e_{2k} h_{2}^{k} \right) = -\sqrt{8} h_{1}^{1} \end{aligned}$$

One knows, that:

(15) $2H = \tilde{g}^{\alpha\beta} b_{\alpha\beta} = \tilde{g}^{\alpha1} b_{\alpha1} + \tilde{g}^{\alpha2} b_{\alpha2} = h_1^1 + h_2^2$ and $b_{11} b_{22} = b_{12} b_{12} + h_1^{\alpha} g_{\alpha1} + h_2^{\alpha} g_{\alpha1}$

$$\mathbf{E} = \frac{\mathbf{b}}{\mathbf{g}} = \frac{\mathbf{b}_{11}^{2} \mathbf{c}_{22}^{2} + \mathbf{b}_{12}^{2} \mathbf{c}_{12}}{\mathbf{g}} = \frac{1}{\mathbf{g}} \begin{vmatrix} \mathbf{h}_{1}^{\alpha} \mathbf{g}_{\alpha,2} & \mathbf{h}_{2}^{\alpha} \mathbf{g}_{\alpha,2} \end{vmatrix}$$
$$= \frac{1}{\mathbf{g}} \begin{vmatrix} \mathbf{h}_{1}^{1} & \mathbf{h}_{2}^{1} \\ \mathbf{h}_{2}^{1} & \mathbf{h}_{2}^{2} \end{vmatrix} \begin{vmatrix} \mathbf{g}_{11} & \mathbf{g}_{12} \\ \mathbf{g}_{12} & \mathbf{g}_{22} \end{vmatrix} = \frac{1}{\mathbf{h}_{1}^{1} \mathbf{h}_{2}^{2} - \frac{1}{\mathbf{h}_{2}^{1} \mathbf{h}_{2}^{2}}{\mathbf{h}_{1}^{2}}$$

The determinant p is:

$$\rho = \det(\rho_{1j}) = \rho_{11}\rho_{22} - (\rho_{12})^2 = -\cosh^2_1h_2^2 - \frac{1}{4}g(h_2^2 - h_1^1)^2 = -\frac{1}{4}g[(h_2^2 - h_1^1)^2 + 4h_1^2h_2^2] = -\frac{1}{4}g[(h_1^1 + h_2^2)^2 - 4h_1^1h_2^2 + 4h_2^1h_2^2] =$$

 $= -\frac{1}{4} g \left[(h_1^1 + h_2^2)^2 - 4(h_1^1 h_2^2 - h_2^1 h_1^2) \right]$

Using (15) and (16) we get:

 $\rho = -\frac{1}{4}g(4H^2 - 4K) = -g(H^2 - K)$

 $H^2 - K$ is always positive, provided that on M^2 there are no umbilical points. Hence ρ is negative. This means, it makes sense to investigate ρ -geodesics on hypersurfaces.

THEOREM 12. Suppose, that on a hypersurface $M^n \subset E^{n+1}$ the set of regular points of the curvature tensor R of the Levi-Civita connection Γ is dense in M^n and det(ρ_{ij}) $\neq 0$. Then ρ -geodesics never coincide with geodesics on M^n . (In other words, there doesn't exist a hypersurface on which ς -geodesics coincide with geodesics).

Proof. On account of the Theorems 4 and 7 we know, that Q-geodesics should have coincided with geodesics if and only if

(18)
$$P_{11} = \alpha g_{11}$$

Multiplying both sides of (18) on g^{jk} and putting k = i, we get:

(19)
$$\rho_{ij} \sigma^{ji} = n \alpha$$

The left hand side of (19) is

$$\begin{aligned} \rho_{ij} \tilde{g}^{ji} &= \frac{1}{2} (\varepsilon_{ip} b_{js} \tilde{g}^{sp} \tilde{g}^{j1} + \varepsilon_{jp} b_{is} \tilde{g}^{sp} \tilde{g}^{j1}) = \\ &= \varepsilon_{ip} b_{js} \tilde{g}^{sp} \tilde{g}^{j1} = 0 \end{aligned}$$

because $\varepsilon_{ip} = -\varepsilon_{pi}$ and $\varepsilon_{jsg}^{sp} = \varepsilon_{jsg}^{ji} = \varepsilon_{jsg}^{si} = \varepsilon_{jsg}^{si}$

T-Geodesics on Hypersurfaces Hence $\alpha = 0$, what leads to a contradiction.

2. T-GEODESICS WITH T BEING OF THE TYPE (1,1).

41

Analogously to the definition of the π -geodesic given by K. Radziszewski [8] we introduce the definition of the π -geodesic in case π is of the type (1,1).

DEFINITION 6. A vector field \overline{w} on a manifold M with a given linear connection Γ is said to be π -geodesic if: $\nabla_{\overline{w}} \mathbf{x}_{\overline{w}} = \lambda \mathbf{x}_{\overline{w}}; \quad \mathbf{T}_{\overline{w}} : \underline{f} \longmapsto \pi(\underline{f}, \overline{w}), \quad \mathbf{f}$ - any covector field on M, where π is non-singular tensor field on M of the type (1,1) and λ is a real differentiable function on M. The integral curve of the π -geodesic vector field on M is called π -geodesic line.

It is easy to show, that in a local map U, the equation of this line is of the form:

(20)
$$\frac{d^2u^{\mathbf{i}}}{dt^2} + (\Gamma^{\mathbf{i}}_{\mathbf{k}\mathbf{j}} + \widetilde{\pi}^{\mathbf{i}}_{\mathbf{p}} \nabla_{\mathbf{k}} \pi^{\mathbf{p}}_{\mathbf{j}}) \frac{du^{\mathbf{k}}}{dt} \frac{du^{\mathbf{j}}}{dt} = \lambda \frac{du^{\mathbf{i}}}{dt}$$

Suppose, that M is Riemannian n-dimensional manifold with the metric tensor g.

or in a local map U:

(22)
$$g_{ij}\pi_k^1 = g_{ik}\pi_j^1$$

Provided that (21) holds, it suffices to observe that the

problem of coincidence of π -geodesics with geodesics on M is the same as the problem of covering geodesics with π^{g} -geodesics in the sense of the definition 1 (π^{g} is a tensor with components $\pi^{1}_{j}g_{ik}$). To can prove:

THEOREM 13. Suppose, that the set of regular points of the curvature tensor R of a Riemannian, connected manifold M is dense in M and there is given a non-singular tensor field T of the type (1,1) on M satisfying (21). Then T-geodesics coincide with geodesics on M if and only if: $T = \lambda \cdot I$.

Proof. Since, the condition of coincidence of T-geodesice with geodesics provided that (21) holds, is equivalent to the problem of coincidence of π^{g} -geodesics with geodesics, then from the Theorems 3 and 7 it follows that:

$$\pi_{j}^{i} \mathbf{E}_{ik} = \lambda \mathbf{E}_{jk} / \mathbf{E}_{ik}$$
$$\pi_{j}^{i} = \lambda \mathbf{S}_{i}^{i} \qquad Q.E.D.$$

Hence

As a special case of this theorem, we have:

THEOREM 14. If $h_{k}^{j} = b_{kl}g^{lj}$ are the components of the non-singular tensor field on a hypersurface $M^{n} \subset E^{n+1}$ with the dense set of regular points of the curvature tensor R, then h-geodesics are the same as geodesics on M^{n} if and only if M^{n} is a sphere (locally).

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STRESZCZENIE

W tej pracy zajmujemy się problemem pokrywania się π -geodezyjnych z geodezyjnymi na hiperpowierzchni Mⁿ ⊂ Eⁿ⁺¹. Pierwszej części rozpatrujemy π-geodezyjne, gdzie π jest naturalny sposób związany z hiperpowierzchnią. W przypadku NY π jest trzecim podstawowym tensorem hiperpowierzchni,

wtedy T-geodezyjne pokrywają się z geodezyjnymi wtedy i tylko wtedy gdy hiperpowierzchnia jest lokalnie sferą, natomiast gdy T jest czwartym podstawowym tensorem powierzchni wtedy nie istnieje hiperpowierzchnia, na której T-geodezyjne pokrywają się z geodezyjnymi.

W drugiej części zajmujemy się **X**-geodezyjnymi wyznaczonymi przez pole tensorowe typu (1,1).

Резюме

В этой работе занимаемся проблемой совпадания Л-геодезических с геодезическими поверхностями М^M \subset Eⁿ⁺¹. В первой части рассматривзем Л -геодезические определимые тензорами, которые натуральным образом связаны с хиперповерхностью. Итак, когда является третим фундаментальным тензором хиперповерхности, тогда для того чтобы Л -геодезические совпадали с геодезическими, необходимо и длстаточно, чтобы хиперповерхность была локально сферой, зато когда Л является четвертым фундаментальным тензором, тогда не существует хиперповерхность, на которой Л -геодезические совпадают с геодезическими.

Во второй части занимаемся X-геодезическими определенными тензорами типа (1,1) .