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## Grassmannian Connections

Koneksje Grassmannowskic
Грассмановы связности

This paper contains an investigation of a second order G-structure over a manifold which is locally Grassmannian in a sense of T. Hangan. There are introduced canonical forms of the two kinds and their structure equations are derived. Then there are obtained invariant connections.

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Throughout all the paper the standard notations of jet calculus are used and, if necessary, they are slightly modified in consistence with notations used in [1], [2] and [3].

## I. The canonical G-structure over a Grassmannian.

Let $F$ denote the field of reals or of complex numbers. We fix the two integers, $p$ and $q$, both $\geqslant 1$ and we set $p+q=n$. We denote by $F^{n}$ the topological product of $n$ sheets of $F$ and we provide $F$ with a natural structure of vector space over $F^{\text {. We denote by }} F_{p}^{q}$ the topological vector space of matrices of the from $\left[x_{a}^{i}\right]_{\substack{i=1, \ldots, q \\ a=1, \ldots, p}}$ We denote by $K$ the unimodular subgroup of $G L(n, F)$ and we have to consider a subgroup $H \subset K$, viz.

$$
H:=\left\{\left[a_{I}^{H}\right]_{H, I=1, \ldots, n} \mid a_{q+\alpha}^{j}=0\right\}
$$

Thus the elements of $H$ are matrices of the form

$$
\left[\begin{array}{c:c}
a_{j}^{i} & 0 \\
\hline a_{j}^{q+a} & a_{\beta}^{a}
\end{array}\right]_{i, j=1, \ldots, a ; a, \beta=1, \ldots, p}
$$

The conventions on ranges of Greek and of Latin indices just used will remain valid in our following considerations.

1. Proposition: $H$ is a stationary group of a p-dimensional plane in $F^{n}$ which is defined by the equations $v^{1}=0, \ldots, v^{q}=0$.
2. Proposition: The homogeneous space $K / H$ is just a Grassmann space of $p$-dimensional subspaces in $F^{n}$.
3. Definition: Let $M$ be a $p q$ dimensional manifold with its support space $M$ and its atlas $A$. Then $M$ is called to be a locally Grassmannian manifold (modelled in $F_{p}^{q}$ ) if:
i) $M$ is locallv modelled in $F_{p}^{q}$.
ii) if ( $U, h$ ) and ( $V, k$ ) are the two local charts in $A$ then there exists a matrix

$$
\left[\begin{array}{c:c}
a^{I} & a^{I I} \\
\hdashline a^{\mathrm{III}} & a^{I \bar{V}}
\end{array}\right] \in K
$$

where $a^{\mathrm{I}} \epsilon \operatorname{hom}\left(F^{q}, F^{q}\right), a^{\mathrm{II}} \epsilon \operatorname{hom}\left(F^{p}, F^{q}\right)=F_{p}^{q}, a^{\mathrm{IV}} \epsilon \operatorname{hom}\left(F^{p}, F^{p}\right)$ and $a^{\text {III }} \epsilon \operatorname{hom}\left(F^{q}, F^{p}\right)$, such that we have for $x \in U \cap V$

$$
\begin{equation*}
k(x)=\left(a^{\mathrm{I}} h(x)+a^{\mathrm{II}}\right)\left(a^{\mathrm{III}} h(x)+\boldsymbol{a}^{\mathrm{IV}}\right)^{-1} \tag{4}
\end{equation*}
$$

(Cf. [1], [2]).
5. Proposition: The Grassmann space of $p$-subspaces in $F^{\prime}$ is a locally Grassmannian manifold. (Cf. [3]).

Let $M$ be a locally Grassmannian manifold modelled in $F_{p}^{q}$. We assume that the atlas which contains all the local charts for which (ii) of def. 3 holds. Then the $r$-jets of of the mappings which are reciprocal to modelling functions are the frames of order $r$ on $M$. The set of these frames is a principal bundle over M. If $r=1$ then the Jacobian matrices of transition functions (4) constitute the structural group, $G$, which is a subgroup of aut $\left(F_{p}^{q}\right)$.

Generally, we denote by $\mathscr{F}_{r} M$ the bundle of admissible $r$-frames on $M$ and we denote by $G_{r}$ a structure group of $\mathscr{F}_{r} M$. We call $\mathscr{F}_{r} M$ the canonical G-structure on $M$.

We shall write the elements of $G$ in at matrix form like

$$
\left[A_{j_{\beta}}^{i_{\alpha}}\right]_{i, j=1, \ldots, \ldots: a, \beta=1, \ldots, p}
$$

The Lie algebra of $K$ (resp. of $H$, resp. of $G$ ) will be denoted by $\mathbf{K}$ (resp. by $\mathbf{H}$, resp. by $\mathbf{G}_{r}$ ).

## II. The canonical form.

Let us fix $r$-frame $A=j_{0}^{r} f, f$ being a diffeomorfism of a neighbourhood of $0 \in F_{t}^{q}$ to $M$. We set $A^{\prime}=j_{0}^{r-1} f$. Let $X$ be a vector tangent to $\mathscr{F}_{r} M$ at $A$. Thus there exists some real interval, $\Delta=\langle-\alpha, \alpha\rangle$ and a mapping $\Delta \rightarrow \mathscr{F}_{r} M / t \rightarrow j_{x \mid 0}^{r} f_{t}(x)$ such that

$$
j_{x \mid 0}^{r} f_{0}(x)=A \quad \text { and } \quad j_{t \mid 0}^{1} j_{x \mid}^{r} \quad f_{t}(x)=X
$$

Thus we have the notation $j_{x \mid 0}^{r} f_{l}(x)$ (resp. $\left.j_{l \mid 0}^{1} f_{t}(x)\right)$ for the $r$-jet of the mapping $x \rightarrow f_{t}(x)$ (and, respectively, of the mapping $t \rightarrow f_{t}(x)$ ), a source being at 0 in $F_{p}^{q}($ resp. 0 in $\Delta)$.

We assume that all $f_{l}(-)$ are admissible so that $X$ is tangent at $\mathscr{F}_{r} M$. If $t$ is proxime to 0 enough then there exists a mapping $f_{0}^{-1} \circ f_{t}$. This is a diffeomorfism of a neighbourhood of 0 in $F_{p}^{q}$ into $F_{p}^{q}$. Thus the vector $j_{t \mid}^{1} j_{x \mid 0}^{r-1} f_{0}^{-1} \circ f_{t}(x)$ depends linearly on $X$ and it is an element of $F_{p}^{q}+\mathbf{G}_{r-1}$, where $\mathscr{O}$ is a vector space tangent to $G_{r-1}$ at its unit element $I_{G}$.

The above construction yields a field of linear forms on $\mathscr{F}_{r} M$ which is called the canonical form of order $r$. Cf. [4], [5], [7], [9], [10], [11].

We denote by $I_{i_{\alpha}}$ the elements of the natural linear basis in $F_{p}^{q}$. Then we denote by $I_{i_{a}}^{j_{\beta}}, \ldots, I_{i_{a}}^{j_{i} \beta_{1} \ldots j_{s} s_{s}}$ the natural linear basis in $\mathbf{G}_{s}$. Now we may. write the following decomposition

$$
\omega^{(r)}=\sum_{i, a} \omega^{i_{a}} \otimes I_{i_{a}}+\sum \omega_{i \beta}^{j_{a}} \otimes I_{a}^{j_{a}}+\ldots+\sum \omega_{j_{1} \beta_{1} \ldots j_{r} \beta_{r}}^{j_{i}} \otimes I_{i_{a}}^{j_{1} \varepsilon_{1}, \ldots j_{r} \beta_{r}}
$$

The following formulas are consequences from general expressions given in [10] and [11]
where $\left[A_{j_{\beta}}^{i_{\alpha}}, A_{j_{\beta} k_{\gamma}}^{i_{\alpha}}\right]$ are local coordinates in a neighbourhood of $A$ in $\mathscr{F}_{2} M$, and the matrix $\left[a_{j_{\beta}^{i}}^{i}\right]$ is reciprocal with respect to $\left[A_{j}^{i} j_{\beta}^{i}\right]$, i.e. $\sum_{k, r} A_{k_{r}}^{i} a_{j}^{i} a_{i r}^{k}=\delta_{j}^{i} \delta_{a}^{B}$.

There hold the following structure equations

$$
\begin{align*}
& d()^{i_{a}}+\sum \omega_{k_{r}}^{i_{a}} \wedge\left(\omega^{k_{r}}=0\right.  \tag{7}\\
& d\left(\omega_{\beta}^{j_{\alpha}}+\sum \omega_{k_{r}}^{i_{r}} \wedge \omega_{\beta}^{k_{r}}+\sum \omega_{j_{\beta} k_{r}}^{i_{r}} \wedge \omega_{k_{r}}=0\right.
\end{align*}
$$

8. Remark: The above construction of $\omega^{(r)}$ may be restricted to vectors tangent of the fibres. Thus we obtain a restricted field of canonical forms, $\bar{\omega}^{(r)}$. It follows immediatelly from formula (6) that we have now

$$
\begin{equation*}
\bar{\omega}^{i_{\alpha}}=0, \quad \bar{\omega}_{\beta}^{i_{\alpha}^{\alpha}}=\sum a_{k_{r}}^{i_{a}^{\alpha}} d A_{j_{\beta}}^{k_{y}} \tag{6bis}
\end{equation*}
$$

$$
\begin{equation*}
d \omega^{i} a=0, \quad d \omega_{j_{\beta}}^{i}+\sum \bar{\omega}_{k_{r}}^{i_{\alpha}} \wedge \bar{\omega}_{j_{\beta}}^{k_{\gamma}}=0 \tag{7bis}
\end{equation*}
$$

Moroover, $\bar{\omega}^{(r)}$ may be defined directly on $\mathscr{F}_{r-1} M$ without performing a projection $A \rightarrow A^{\prime}$ because $\omega^{(r)}$ does not depend on the coordinates of the highest order of the frame.

$$
\begin{align*}
& (1)^{i_{a}}=\sum a_{k_{r}}^{i_{d}} d x_{r}^{k} \\
& \omega_{j_{\beta}^{i}}^{i_{a}}=\sum a_{k_{r}}^{i_{a}}\left(d A_{j_{\beta}}^{k_{r}}-\sum A_{p_{p} t_{0}}^{k_{r}} \omega^{l^{l_{\delta}}}\right) \tag{6}
\end{align*}
$$

9. Theorem: Let $\varphi=\Sigma \varphi_{p}^{i_{p}} \otimes I_{i \alpha}^{j_{\beta}}$ be a form of some linear connection on $M$, more exactly on $\mathscr{F}_{1} M$. Then there exists a field of linear forms on $\mathscr{F}_{2} M$

$$
A \rightarrow \sum I_{k_{r} \beta_{\beta}}^{i_{a}}(A) \omega_{A}^{k_{i}} \otimes I_{i_{a}}^{j \beta}
$$

such that:
$1^{0}$ the form $\Sigma\left(\omega_{j_{\beta}}^{i_{a}}+\Sigma I_{i_{r}^{i} j_{\beta}}^{i_{j}} \omega^{k_{r}}\right) \otimes I_{i_{a}^{\beta}}^{j_{\beta}}$ depends only on the projection $A^{\prime}$ of $A$, $2^{\circ}$ the following system of differential equations is satisfied
where $\Sigma \Gamma_{k_{r} j_{\beta}, l_{l}}^{i_{2}} I_{e_{a}}^{k_{r} j_{\beta} l_{l}}$ is a certain linear form on $\mathscr{F}_{3} M$.
Proof. The system of forms $\left[\omega^{i_{\alpha}}, \omega_{j_{\beta}}^{i_{\beta}}\right]$ constitutes a co-frame at each point $A^{\prime}$ of $\mathscr{F}_{1} M$. Thus the $\varphi$-horizontal subspaces tangent to $\mathscr{F}_{1} M$ at $A^{\prime}$ is given by a system of linear equations of the form

$$
\omega_{j_{\beta}^{\alpha}}^{j_{\alpha}}+\sum \Gamma_{k_{r} j_{\beta}}^{i_{\alpha}} \omega^{k_{r}}=0
$$

where $\left[\Gamma_{k_{r} j_{\beta}}^{i \alpha}\right.$ ] depend on $A$ as $\left[\omega_{\beta_{\beta}}^{i \alpha}\right]$ do. Then the statement $2^{\circ}$ follows by remark 8 . In order to prove $2^{\circ}$ we introduce into considerations the curvature tensor, $R$, of $\varphi$ and we make from the definition equality

$$
d \varphi_{j_{\beta}}^{i_{\alpha}}+\sum \varphi_{k_{r}}^{i_{\alpha}} \wedge \varphi_{\beta_{\beta}}^{k}=\sum R_{k_{x} \lambda_{\lambda} j_{\beta}}^{i_{\alpha}} \omega^{h_{\star}} \wedge \omega^{l_{\lambda}}
$$

We substitute $\omega_{j_{\beta}}^{i \alpha}+\Sigma T_{k_{r} j_{\beta}}^{i_{j_{\beta}}} \omega_{k_{r}}$ in a place of $\varphi_{j_{\beta}^{\alpha}}^{i \alpha}$ and we obtain the following equalities

$$
\begin{align*}
& \left.-\omega_{k_{r} j_{\beta}}^{i_{a}}-\sum\left(\Gamma_{l_{\lambda} h_{\sigma}}^{j_{\sigma}} \Gamma_{k_{r} j_{\beta}}^{h_{j_{\beta}}}+R_{l_{k} k_{r} j_{\beta}}^{i}\right) \omega^{l_{\lambda}}\right\} \wedge \omega^{k_{r}}=0 \tag{*}
\end{align*}
$$

In power of the generalized lemmab of Cartan ${ }^{+}$) we conclude that there
 the parantheses in (*) are equal to

[^0]
## III. The canonical form of the second kind

Let us turn to the frame $A=j_{0}^{r} f$. If $a \in K$ then we set $a_{*} A:=j_{0}^{r} f\left(a^{-1} y\right)$ where we denote by ay as result of the action of $K$ on $F$ according to the rule: If

$$
g=\left[\begin{array}{c:c}
g^{\mathrm{I}} & g^{\mathrm{II}} \\
\hline g^{\mathrm{III}} & g^{\mathrm{IV}}
\end{array}\right] \in K
$$

then

$$
\begin{equation*}
g y=\left(g^{\mathrm{I}} y+g^{\mathrm{II}}\right)\left(g^{\mathrm{III}} y+g^{\mathrm{IV}}\right)^{-1} \tag{10}
\end{equation*}
$$

We observe that the action * implies a homomorfism of K into the Lie algebra of vector fields on $\mathscr{F}_{r} M$. Then a vector field on $\mathscr{F}_{r} M$ which is generated by a vector $X \in \mathrm{~K}$ will be denoted by $X^{(r)}$.

We define a canonical form of the second kind, $\theta^{(r)}$, as follows

$$
\begin{equation*}
o_{A}^{(r)}(X):=\omega_{A}^{(r)}\left(X^{(r)}\right) \tag{11}
\end{equation*}
$$

The following proposition follows directly from the considerations of the previous section.
12. Proposition: If $Y \in \mathbb{H}$ then $Y^{(r-1)}$ is a vertical field on $\mathscr{F}_{r-1} M$. Consequently we have

$$
\theta_{A^{1}}^{(r-1)}(Y)=\bar{\omega}_{A^{\prime}}^{(r-1)}\left(Y_{A^{\prime}}^{(r-1)}\right)=\psi_{A^{\prime}}^{(r-1)}\left(Y_{A^{1}}^{(r-1)}\right)
$$

for any connection form $\psi^{(r-1)}$ on $\mathscr{F}_{r-1} M$.
We are going to obtain a local expression for $0^{(r)}$. Let $t \rightarrow a_{t}$ describe a curve in $K$ which starts from $I_{k}$, such that $X=j_{t ; 0}^{l} a_{l}$. Then the mapping $f^{-1}$, such that $A=j_{0}^{r} f$, yields some local chart in a neighbourhood of $A$. The coordinates of $A$ are $\left(0,\left[\delta_{j}^{i} \delta_{a}^{d}\right], 0, \ldots, 0\right)$. Moreover, this chart defines a local cross-section through $A$ in $\mathscr{F}_{r} M$. In consistence with the construction of the form $0^{(r)}$ we have

$$
\begin{equation*}
\theta_{A}^{(r)}(X)=j_{t \mid 0}^{1} j_{x \mid 0}^{r-1} f^{-1}\left(\left(a_{t}^{-1}\right) \cdot x\right)=j_{t \mid 0}^{1} j_{x \mid 0}^{r-1} f^{-1} a_{t}^{-1} x \tag{13}
\end{equation*}
$$

We split $\theta^{(r)}$ into components

We introduce into considerations the canonical left-invariant form $\vartheta=\left[\vartheta_{I}^{i}\right]$ on $K$. We perform the computations in details according to (13) and we replace the components of $X$ by the corresponding components
of $\vartheta$. Then we obtain the following local expressions of the components of $\theta^{(3)}$ :
16. Lemma: The forms

$$
\varphi_{j}^{\beta}:=\varphi_{j}^{i}-x_{\lambda}^{i} \varphi_{j}^{2} \quad \text { and } \quad \psi_{a}^{\beta}:=\varphi_{a}^{\beta}+\varphi_{k}^{\beta} x_{a}^{k}
$$

satisfy the following identities

$$
\begin{aligned}
& d \psi_{j}^{i}+\psi_{k}^{i} \wedge \psi_{j}^{k}+\vartheta^{i_{\lambda}} \wedge \varphi_{j}^{\lambda}=0 \\
& d \psi_{a}^{\beta}+\psi_{\mu}^{\beta} \wedge \psi_{a}^{A}+\psi_{j}^{\beta} \wedge \vartheta^{j a}=0
\end{aligned}
$$

Proof: We make use from the identities of Maurer and Cartan

$$
\begin{gathered}
d \varphi_{j}^{i}=-\varphi_{k}^{i} \wedge \varphi_{j}^{k}-\varphi_{a}^{i} \wedge \varphi_{j}^{a}, \\
d \varphi_{j}^{\lambda}=-\varphi_{k}^{\lambda} \wedge \varphi_{j}^{k}-\varphi_{a}^{\lambda} \wedge \varphi_{j}^{a},
\end{gathered}
$$

etc.

Then we have $d \psi_{j}^{\lambda}=d \varphi_{j}^{i}-d x^{i_{\lambda}} \wedge \varphi_{j}^{\lambda}-x^{i \lambda} d \varphi_{j}^{i}$ and we replace $d x^{i_{\lambda}}$ by its expression which will be obtained from the formula of $\vartheta^{〔}$. Then we obtain our lemma by performing some easy reduction.
17. Theorem: The components of $0^{(3)}$ satisfy the following identities

Proof: By a skew differentiation of (15) and by making use from lemma 16.

In order to investigate better the canonical $G$-structure on $M$ we have to introduce new coordinates in $\mathrm{G}_{2}$. We put
and

$$
\psi_{a}^{i}=\vartheta^{i_{a}}, \psi_{j}^{\mu}=\vartheta_{j}^{\mu}
$$

$$
\begin{aligned}
& J_{a}^{\beta}=-\sum \mathrm{I}_{k_{\beta},}^{k_{a}}, \mathrm{~J}_{j}^{\ell}=-\sum \mathrm{I}_{k}^{k} \\
& J_{\lambda}^{i}=-\sum\left(\mathrm{I}_{x}^{j}{ }_{x}^{j_{\lambda}}+\mathrm{I}_{x}^{L_{x}^{\prime} j_{x}}\right), \quad J_{i}^{\lambda}=\mathrm{I}_{i_{\lambda}}
\end{aligned}
$$

$$
\begin{aligned}
& d \vartheta^{i_{a}}+\sum_{j, \beta} \theta_{j_{\beta}^{j_{\alpha}} \wedge}^{\theta^{j_{\beta}}}=0 \\
& d \vartheta_{j_{\beta}}^{i_{a}}+\sum \vartheta_{k_{r}}^{i} \wedge \vartheta_{j_{\beta}}^{k_{r}}+\sum \vartheta_{j_{r} k_{r}}^{i} \wedge \vartheta^{k_{r}}=0
\end{aligned}
$$

$$
\begin{align*}
& \theta^{i}{ }^{i}=d x_{a}^{i}+\vartheta_{j}^{i} x_{a}^{j}+\vartheta_{a}^{i}-x_{\beta}^{i} \vartheta_{j}^{\beta} x_{a}^{j}-x_{\beta}^{i} \psi_{a}^{\beta} \\
& \theta_{j \beta}^{i a}=\left(\vartheta_{j}^{i}-x_{r}^{i} \vartheta_{j}^{r}\right) \delta_{a}^{\beta}+\left(-\vartheta_{a}^{\beta}-\vartheta_{k}^{\beta} x_{a}^{i}\right) \delta_{j}^{i}  \tag{15}\\
& \theta_{j}^{j} \beta_{p}^{\alpha}=-\vartheta_{j}^{r} \delta_{k}^{i} \delta_{a}^{\beta}-\vartheta_{k}^{\beta} \delta_{j}^{j} \delta_{a}^{r} \\
& \vartheta_{j_{1} \beta_{1} j_{2} \beta_{2} j_{3} \theta_{3}}^{i_{1}}=0 \quad \text { etc. }
\end{align*}
$$

Then we may write the decomposition (14) in a following form

$$
\begin{equation*}
\theta^{(3)}=\psi_{a}^{i} \otimes J_{i}^{a}+\psi_{j}^{i} \otimes J_{j}^{j}+\psi_{a}^{\beta} \otimes \cdot J_{\beta}^{a}+\psi_{j}^{\mu} \otimes J_{\mu}^{j} \tag{18}
\end{equation*}
$$

19. Theorem: There hold the following structure equations

$$
\begin{aligned}
& \boldsymbol{d} \psi_{a}^{i}+\psi_{j}^{i} \wedge \psi_{a}^{j}+\psi_{\beta}^{i} \wedge \psi_{a}^{\beta}=\mathbf{0} \\
& d \psi_{j}^{i}+\psi_{k}^{i} \wedge \psi_{j}^{k}+\psi_{a}^{i} \wedge \psi_{j}^{a}=\mathbf{0} \\
& \boldsymbol{d} \psi_{a}^{\beta}+\psi_{k}^{B} \wedge \psi_{a}^{k}+\psi_{a}^{\beta} \wedge \psi_{a}^{\lambda}=0 \\
& \boldsymbol{d} \psi_{j}^{a}+\psi_{k}^{a} \wedge \psi_{j}^{k}+\psi_{\beta}^{a} \wedge \psi_{j}^{\beta}=\mathbf{0}
\end{aligned}
$$

Moreover, the equality $(\Sigma) \vartheta_{i}^{i}+\vartheta_{a}^{a}=\mathbf{0}$ implies $\psi_{i}^{i}+\boldsymbol{\psi}_{a}^{a}=\mathbf{0}$.
Proof: The theorem follows easily by writing out the identities in theorem 17 and by using the formulae (15) in a new form

$$
\begin{aligned}
& \theta_{j_{\beta}^{j}}^{j}=\psi_{j}^{f} \delta_{a}^{b}-\psi_{d}^{\beta} \delta_{j}^{d}, \\
& \sum{ }_{j}^{\theta_{p}^{j}} \otimes \mathrm{I}_{a}^{j}=\psi_{j}^{i} \otimes J_{i}^{j}+\psi_{a}^{\beta} \otimes J_{\beta}^{a} \\
& \sum \theta_{j}^{i_{a_{r}}} \otimes \mathrm{I}_{a}^{j}{ }_{a}^{k_{\gamma}}=\psi_{j}^{\beta} \otimes J_{\beta}^{j}
\end{aligned}
$$

Then we are able to prove the main theorem.
20. Theorem: The structure group of $\mathscr{F}_{2} M$ is isomorphic to the stationary group $H$.

Proof: In order to obtain the fibre forms we assume $\theta^{i \alpha}\left(=\varphi_{a}^{\prime}\right)=0$. Thus the Lie algebra the structure group is spanned on the basic vectors $\mathbf{I}_{j}^{i}, \mathbf{I}_{a}^{\beta}, \mathbf{I}_{\beta}^{j}$. The values of Poisson brackets may be obtained directly from the structure equations of the components of $\psi$ Cf. [17]. These are just consistent with the structure equations of $H$. Taking into account the identity $\psi_{i}^{i}+\psi_{a}^{\alpha}=0$ and the fact that all the groups under consideration are connected we obtain the theorem.

If we restrict our above considerations to the bundle $\mathscr{F}_{1} M$ then we obtain the following theorem [2]:
21. Theorem: The structure group of $\mathscr{F}_{1} M$ is izomorfic to $(G L(p, F) \times$ $\times G L(q, F)) \cap S L(p+q, F)$.

## IV. The connections.

From now we assume that $K$ acts on $M$ (at least locally) transitively from the left in such a way that this action is expressed by the generalized homografy (4) in any admissible local coordinates. We denote this left--action by $\tau$ and this same notation will be used for an induced left action on
$\mathscr{F}_{2} M$. We have to look for connections on the bundle $F_{2} M$ which are invariant with respect to $\tau$. These will be called the Grassmannian connections.

To begin with we fix a frame $u=j_{0}^{1} f$ and we define a mapping $\lambda: H \rightarrow G_{2}$ as follows

$$
\lambda(h)=j_{x \mid 0}^{2} f^{-1} \circ \tau_{h} \circ f(x)
$$

We put also

$$
\lambda^{+}: \mathbf{H} \rightarrow \mathbf{G}_{2} / \lambda^{+}\left(j_{t \mid 0}^{1} h_{t}\right)=j_{t \mid 0}^{1} \lambda\left(h_{t}\right)
$$

Then we compute the explicit expression $\lambda^{+}$in local coordinates which are determined by $f^{-1}$. We obtain

$$
\lambda^{+}=\left(\psi_{j}^{i} \otimes J_{i}^{j}+\psi_{a}^{\beta} \otimes J_{\beta}^{a}+\psi_{j}^{\beta} \otimes J_{\beta}^{j}\right)_{\mid u}
$$

If we take into account the fact the components $\psi_{j}^{i}, \psi_{\beta}^{a}, \psi_{j}^{\beta}$ do not depend on $\vartheta_{a}^{i}$ then we observe that there holds the following
22. Proposition: We have

$$
\lambda^{+}=\left.\theta^{(2)}\right|_{x=0,}, \vartheta^{i} a=0
$$

Now we may apply the theorem of Wang (Cf. [12] [6]) which claimes that:

There holds a 1-1 correspondence between the invariant connections and the forms $\Lambda: K \rightarrow \mathrm{G}_{2}$ such that ( $\left.\alpha\right) \Lambda \mid \mathbf{H}=\lambda^{+}$, and $(\beta) \Lambda \circ a d j_{h}=a d j_{(h)} \Lambda$ This correspondence is given by the relation $\varphi_{u} \circ \tau^{+}=\Lambda$ where $\varphi$ is ac connection form and $\tau^{+}: \mathbf{K} \rightarrow \boldsymbol{T} \mathscr{F}_{2} M$ is induced by $\tau$.

It follows by the proposition that the condition (a) may be replaced by the following

$$
\begin{equation*}
\Lambda=\lambda^{+}+\Sigma \psi_{r}^{k} \otimes\left(J_{j}^{i} \Gamma_{k_{r},}^{j}+J_{\beta}^{a} \Gamma_{k_{r} a}^{\beta}+\boldsymbol{J}_{\beta}^{j} \Gamma_{k_{r} j}^{\beta}\right) \tag{23}
\end{equation*}
$$

In view of connectedness of $K$ and $H$ we may also reformulate ( $\beta$ ) into an infinitesimal form. We take a vector

$$
Y=j_{t \mid 0}^{1} h_{t} \epsilon \mathbf{H}
$$

and we obtain

$$
\begin{align*}
& \Lambda([Y, X])=j_{t 0}^{1} \Lambda\left(a d j_{h_{t}} X\right)=j_{t 0}^{1} \lambda\left(h_{t}\right) \cdot \Lambda(X) \cdot\left(\lambda\left(h_{t}\right)\right)^{-1}  \tag{24}\\
& \quad=\lambda^{+}(Y) \cdot \Lambda(X)-\Lambda(X) \cdot \lambda^{+}(Y)=\left[\lambda^{+}(Y), \Lambda(X)\right]
\end{align*}
$$

We substitute the right-hand member of (23) for $\Lambda$. In view of the fact that $\lambda^{+}$is a Lie homomorfism we obtain the following condition which is equivalent to ( $\beta$ ):

$$
\begin{equation*}
\Gamma([\boldsymbol{Y}, X])=\left[\lambda^{+}(\mathbf{Y}), \Gamma(X)\right] \quad \text { for } \quad Y \in \mathbf{H}, X_{\epsilon} \mathbf{K} \tag{25}
\end{equation*}
$$

where $\Gamma=\Lambda-\lambda^{+}$. A dimension of the vector space $\mathbf{H}+\mathbf{K}$ is equal to $\left(p^{2}+q^{2}+p q\right)(p+q)^{2}$ and there are to be determined from (25) $\left(p^{2}+q^{2}+\right.$ $+p q) p q$ numbers $I_{k M M}^{T L}$. If we write (25) explicitely then we see that it yields a system of linear homogeneous equations which has $\left(p^{2}+q^{2}+p q\right)^{2}$ independent solutions. Then the theorem of Wang applied to our case yields the following theorem.
26. Theorem: There exists a $\left(p^{2}+q^{2}+p q\right)^{2}$-parametric family of Grassmannian connections on M. These connections are in a 1-1 correspondence with the solutions of (25).

In order to obtain some informations on a curvature $R$ we make use from the following formula (Cf. [6] Ch. X):

$$
R(\tilde{X}, \tilde{Z})=u \circ\left([\Lambda(X), \Lambda(Z)]-\Lambda([X, Z]) \circ u^{-1}\right.
$$

where $X$ and $Z$ are vectors $\epsilon \mathrm{K}$ and $\tilde{X}, \tilde{Z}$ are their canonical maps at $u$. An easy transformation of the above formula yields the following

$$
\begin{aligned}
R(\tilde{X}, \tilde{Z})=u \circ\left(\left[\Gamma(X), \lambda^{+}(Z)\right]-\right. & {\left[\Gamma(Z), \lambda^{+}(Y)\right]+} \\
& +[\Gamma(X), \Gamma(Z)]-\Gamma([X, Z)]) \circ u^{-1}
\end{aligned}
$$

This formula implies immediately the following theorem [3].
26. Theorem. The canonical Grassmannian connection which corresponds to a case $I^{\prime}=0$ has the curvature equal to zero.

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## STIRESZCZENIE

Praca zawiera konstrukcje formy kanonicznej 1-go i 2 -go rodzaju na rozmaitości Grassmanna $p$-wymiarowego plaszczyzn w $n$-wymiarowej przestrzeni wektorowej. Na rozmaitósci tej, rozpatrywanej jako przestrzeú Kleina mamy naturalną $G$-strukturę rzędu drugiego. Wlasności grupy strukturowej otrzymujemy w prosty sposób poprzez własności formy kanonicznej 2-go rodzaju. Specjalizując twierdzenic G. C. Wanga o niezmienniczych koneksjach na rozınaitościach jednorodnych otrzymujemy twierdzenie o istnieniu ( $\left.p^{2}+q^{2}+p q\right)^{2}$-parametrowej rodziny niezmienniczych koneksji na omawianej $G$-strukturze. Dokładnie jodna z nich, kanoniczna, jest koneksja, otrzymana i zbadaną przez Th. Hangana.

## P E 3 Ю M E

В работе содержится конструкция канонической формы 1-го и 2 -го рода на Грассмановом многообразии $p$-размерных плоскостей $n$-мерного векторного пространства. На этом многообразии, рассматриваемом как пространство Клейна, получаем соответственно $G$-структуру второго порядка. Свойства структурной группы получаем из свойств канонической формы 2 -го рода. Пользуясь теоремой Ванга о6 инвариантных связностях на однородных пространствах, получаем теорему о существовании ( $\left.p^{2}+q^{2}+p q\right)^{2}$ - параметрического семейства связностей изучаемой $G$-структуры. Одна из них, а именно каноническая, является связностью, полученной и изученной Т. Хантаном.


[^0]:    ${ }^{+}$) The lemma of Cartan generalized by G. F. Laptev may be formulated as follows: Let $v_{1}, \ldots, v_{a}$ be alinearly independent elements of a finite-dimensional vector space $\nabla$. If the elements $\bar{Y}_{1}, \ldots, Y_{a}$ of the exterior product $\Lambda^{p} V$ satisfy the equality $\sum_{i} Y_{i} v_{i}=0$ then there exist in $\wedge^{p-1} V$ some $z_{i k}$ such that $z_{i k}=z_{k}$ and $Y_{i}$ $=\sum_{j=1}^{x} z_{i j} v_{j}$. Cf. [10]. Recently Mr. O. Kowalski in Praha has obtained a profound generalization [8].

