# ANNALES <br> UNIVERSITATIS MARIAE CURIE-SKもODOWSKA <br> LUBLIN - POLONIA <br> VOL. LIX, 2005 

## On covering problems

 in the class of typically real functions
#### Abstract

Let $A$ be a class of analytic functions on the unit disk $\Delta$. In this article we extend the concept of the Koebe set and the covering set for the class $A$. Namely, for a given $D \subset \Delta$ the plane sets of the form $$
\bigcap_{f \in A} f(D) \text { and } \bigcup_{f \in A} f(D)
$$ we define to be the Koebe set and the covering set for the class $A$ over the set $D$. For any $A$ and $D=\Delta$ we get the usual notion of Koebe and covering sets. In the case $A=T$, the normalized class of typically real functions, we describe the Koebe domain and the covering domain over disks $\{z:|z|<r\} \subset \Delta$ and over the lens-shaped domain $H=\{z:|z+i|<\sqrt{2}\} \cap\{z:|z-i|<\sqrt{2}\}$.


Introduction. Let $\mathcal{A}$ be the family of all analytic functions $f$ on the unit disk $\Delta=\{z \in \mathbf{C}:|z|<1\}$, normalized by $f(0)=f^{\prime}(0)-1=0, A \subset \mathcal{A}$ and let $D$ be a subdomain of $\Delta$ with $0 \in D$. The plane sets $K_{A}(D)=$ $\bigcap_{f \in A} f(D), L_{A}(D)=\bigcup_{f \in A} f(D), K_{A}=K_{A}(\Delta)$ and $L_{A}=L_{A}(\Delta)$ we shall call the Koebe domain for the class $A$ over the set $D$, the covering domain for the class $A$ over the set $D$, the Koebe domain for the class $A$ and the covering domain for the class $A$, respectively. Except some special cases, the sets $K_{A}(D)$ are open connected and hence domains. Note that for

[^0]$$
A=\left\{z \mapsto \frac{1}{a}\left(e^{a z}-1\right): a \in \mathbf{C} \backslash\{0\}\right\}
$$
and
$$
B=\left\{z \mapsto \frac{1}{2 n}\left[\left(\frac{1+z}{1-z}\right)^{n}-1\right]: n=m, m+1, m+2, \ldots\right\},
$$
$m>0$, we have $K_{A}=\{0\}$, and hence $K_{\mathcal{A}}=\{0\}$, and the sets $K_{B}$ are not open. For many important classes, the Koebe domains were discussed in a number of papers and some sharp results are well known (see [4] for more details).

The determination of sets $K_{A}$ and $L_{A}$ is usually more difficult if the considered classes are not rotation invariant, which means that the following property

$$
\begin{equation*}
f \in A \Leftrightarrow e^{-i \varphi} f\left(z e^{i \varphi}\right) \in A \quad \text { for any } \quad \varphi \in \mathbf{R} \tag{1}
\end{equation*}
$$

is not satisfied.
For instance, (1) is not satisfied by each nontrivial class $A$ with real coefficients. One of them is the class $T$ of typically real functions, i.e. functions $f \in \mathcal{A}$ and satisfying the condition

$$
\operatorname{Im} z \operatorname{Im} f(z) \geq 0 \quad \text { for } \quad z \in \Delta
$$

The Koebe domain for the class $T$ was found by Goodman [3].
Theorem A (Goodman). The Koebe domain for the class $T$ is symmetric with respect to both axes, and the boundary of this domain in the upper half plane is given by the polar equation

$$
\varrho(\theta)= \begin{cases}\frac{\pi \sin \theta}{4 \theta(\pi-\theta)} & \text { for } \theta \in(0, \pi), \\ \frac{1}{4} & \text { for } \theta=0 \text { or } \theta=\pi .\end{cases}
$$

The covering domain for the class $T$ is the whole plane because for members $f_{1}(z)=\frac{z}{(1-z)^{2}}$ and $f_{-1}(z)=\frac{z}{(1+z)^{2}}$ we have $f_{1}(\Delta) \cup f_{-1}(\Delta)=\mathbf{C}$.

Clearly, each time if $\left\{f_{1}, f_{-1}\right\} \subset A \subset \mathcal{A}$ then $\mathbf{C}$ is the covering domain for $A$. However, for many classes the covering domain may give some interesting information (like for classes of bounded functions).

Basic properties of $K_{A}(D)$ and $L_{A}(D)$ established in the following two theorems are easy to prove.

First, let us denote by $\partial D$ the boundary of a set $D$. Moreover, we use the notation:

$$
\begin{aligned}
\Delta_{r} & =\{z \in \mathbf{C}:|z|<r\} \\
S & =\{f \in \mathcal{A}: f \text { is univalent in } \Delta\} \\
\mathcal{A} R & =\{f \in \mathcal{A}: f \text { has real coefficients }\} .
\end{aligned}
$$

Theorem 1. For a fixed class $A \subset \mathcal{A}$, the following properties of $K_{A}(D)$ are true:

1. if $A$ satisfies (1) and $A \subset S$, then $K_{A}\left(\Delta_{r}\right)=\Delta_{m(r)}$, where $m(r)=$ $\min \left\{|f(z)|: f \in A, z \in \partial \Delta_{r}\right\} ;$
2. if $A \subset \mathcal{A R}$ and $D$ is symmetric with respect to the real axis, then $K_{A}(D)$ is symmetric with respect to the real axis;
3. if $A \subset \mathcal{A} R$ consists of only such $f$ that $-f(-z) \in A$, and if $D$ is symmetric with respect to both axes, then $K_{A}(D)$ is symmetric with respect to both axes;
4. if $D_{1} \subset D_{2}$, then $K_{A}\left(D_{1}\right) \subset K_{A}\left(D_{2}\right)$;
5. if $A_{1}, A_{2} \subset \mathcal{A}$ and $A_{1} \subset A_{2}$, then $K_{A_{2}}(D) \subset K_{A_{1}}(D)$.

Theorem 2. For a fixed class $A \subset \mathcal{A}$, the following properties of $L_{A}(D)$ are true:

1. if $A$ satisfies (1) and $A \subset S$, then $L_{A}\left(\Delta_{r}\right)=\Delta_{M(r)}$, where $M(r)=$ $\max \left\{|f(z)|: f \in A, z \in \partial \Delta_{r}\right\} ;$
2. if $A \subset \mathcal{A} R$ and $D$ is symmetric with respect to the real axis, then $L_{A}(D)$ is symmetric with respect to the real axis;
3. if $A \subset \mathcal{A} R$ consists of only such $f$ that $-f(-z) \in A$, and if $D$ is symmetric with respect to both axes, then $L_{A}(D)$ is symmetric with respect to both axes;
4. if $D_{1} \subset D_{2}$, then $L_{A}\left(D_{1}\right) \subset L_{A}\left(D_{2}\right)$;
5. if $A_{1}, A_{2} \subset \mathcal{A}$ and $A_{1} \subset A_{2}$, then $L_{A_{1}}(D) \subset L_{A_{2}}(D)$.

In accordance with simple results concerning the known classes $S, S T$, $C V$ and $C C$ consisting of normalized univalent, starlike, convex and close-to-convex functions respectively, we have

$$
K_{S}\left(\Delta_{r}\right)=K_{S T}\left(\Delta_{r}\right)=K_{C C}\left(\Delta_{r}\right)=\Delta_{m(r)}
$$

where $m(r)=\frac{r}{(1+r)^{2}}, r \in(0,1]$,

$$
K_{C V}\left(\Delta_{r}\right)=\Delta_{m(r)}
$$

where $m(r)=\frac{r}{1+r}, r \in(0,1]$,

$$
L_{S}\left(\Delta_{r}\right)=L_{S T}\left(\Delta_{r}\right)=L_{C C}\left(\Delta_{r}\right)=\Delta_{M(r)}
$$

where $M(r)=\frac{r}{(1-r)^{2}}, r \in(0,1)$,

$$
L_{C V}\left(\Delta_{r}\right)=\Delta_{M(r)}
$$

where $M(r)=\frac{r}{1-r}, r \in(0,1)$,

$$
L_{S}(\Delta)=L_{S T}(\Delta)=L_{C C}(\Delta)=L_{C V}(\Delta)=\mathbf{C}
$$

In this paper we determine Koebe domains and covering domains for the class $T$ over some special sets, like disks $\Delta_{r}$ and the lense-shaped domain $H=\{z:|z+i|<\sqrt{2}\} \cap\{z:|z-i|<\sqrt{2}\}$.

Covering domains $\boldsymbol{L}_{\boldsymbol{T}}(\boldsymbol{D})$. First of all, let us consider the case $D=\Delta_{r}$, where $r \in(0,1)$. Since the class $T$ does not satisfy (1), the set $L_{T}\left(\Delta_{r}\right)$ is not equal to $\Delta_{M(r)}$, where $M(r)=\max \left\{|f(z)|: f \in T, z \in \partial \Delta_{r}\right\}=\frac{r}{(1-r)^{2}}$, but is a proper subset of $\Delta_{M(r)}$.

Denote

$$
\begin{equation*}
f_{t}(z)=\frac{z}{1-2 z t+z^{2}}, t \in[-1,1] \tag{2}
\end{equation*}
$$

These functions are univalent, starlike in the unit disk and

$$
\begin{equation*}
E T=\left\{f_{t}(z): t \in[-1,1]\right\} \tag{3}
\end{equation*}
$$

where $E T$ means the set of extreme points of the class $T$ (see for example [5]). The following lemma is true for the functions of the form (2).
Lemma 1. For $t \in[0,1]$ we have $f_{-t}\left(\Delta_{r}\right) \cap\{w: \operatorname{Re} w>0\} \subset f_{t}\left(\Delta_{r}\right) \cap\{w:$ $\operatorname{Re} w>0\}$.
Proof. The above inclusion is true for $t=0$. Let $t \in(0,1]$. If $1 / f_{t}(z)=$ $1 / f_{-t}(\zeta)=u+i v$ and $|z|=|\zeta|=r$ then

$$
\left(\frac{u+2 t}{r+1 / r}\right)^{2}+\left(\frac{v}{1 / r-r}\right)^{2}=1=\left(\frac{u-2 t}{r+1 / r}\right)^{2}+\left(\frac{v}{1 / r-r}\right)^{2}
$$

i.e. $u=0, v^{2}=\left[\left(1+r^{2}\right)^{2}-4 t^{2} r^{2}\right]\left(1-r^{2}\right)^{2} /\left(r+r^{3}\right)^{2}, z=\frac{2 t r^{2}}{1+r^{2}}-i \frac{v r^{2}}{1-r^{2}}$, $\zeta=-\bar{z}$. Thus

$$
f_{t}\left(\partial \Delta_{r}\right) \cap f_{-t}\left(\partial \Delta_{r}\right)=\{i \varrho,-i \varrho\}
$$

where

$$
\varrho=1 /|v|=\left(r+r^{3}\right) /\left[\left(1-r^{2}\right) \sqrt{\left(1+r^{2}\right)^{2}-4 t^{2} r^{2}}\right] .
$$

The inequality $f_{t}(r)>f_{-t}(r)$ completes the proof.
By the Robertson formula for the class $T$, the set $\{f(z): f \in T\}$ is the closed convex hull of the circular arc $\left\{f_{t}(z):-1 \leq t \leq 1\right\}$, so we have [2]:
Theorem B (Goluzin). Let $z=r e^{i \varphi} \in \Delta \backslash\{0\}, 0<\varphi<\pi$ and $R=$ $r /\left[2\left(1-r^{2}\right) \sin \varphi\right.$. The set $\{f(z): f \in T\}$ is the closed convex segment bounded by the arc $\left\{f_{t}(z):-1 \leq t \leq 1\right\}$ and the line segment joining the points $f_{1}(z), f_{-1}(z)$. Clearly, $\left\{f_{t}(z):-1 \leq t \leq 1\right\} \subset\{w:|w-i R|=R\}$.

One can obtain from this theorem that the upper estimate of the set of moduli of typically real functions in a fixed point $z \in \Delta$ is attained by the functions of the form (2). The lower estimation is attained by a suitable function of the form

$$
\begin{equation*}
f=\alpha f_{1}+(1-\alpha) f_{-1}, \alpha \in[0,1] \tag{4}
\end{equation*}
$$

Let $r$ be an arbitrary fixed number in $(0,1)$.

Theorem 3. $L_{T}\left(\Delta_{r}\right)=f_{1}\left(\Delta_{r}\right) \cup f_{-1}\left(\Delta_{r}\right)$.
Proof. The property 3 from Theorem 2 gives that the covering domain $L_{T}\left(\Delta_{r}\right)$ is symmetric with respect to both coordinate axes. It suffices to determine the boundary of this set only in the first quadrant of $\mathbf{C}$ plane.

To do this, we discuss

$$
\begin{equation*}
\max \{|f(z)|: f \in T,|z|=r, \arg f(z)=\alpha\}, \alpha \in\left[0, \frac{\pi}{2}\right] \tag{5}
\end{equation*}
$$

According to Theorem B, we have

$$
\begin{align*}
\max \{|f(z)| & : f \in T,|z|=r, \arg f(z)=\alpha\} \\
& =\max \left\{\left|f_{t}(z)\right|: t \in[-1,1],|z|=r, \arg f_{t}(z)=\alpha\right\} \tag{6}
\end{align*}
$$

Clearly, the maximum of the right hand side of (6) is obtained by some $f_{t_{0}}$ if and only if the minimum

$$
\begin{equation*}
\min \left\{\frac{1}{4}\left|f_{t}(z)\right|^{-2}: t \in[-1,1],|z|=r, \quad \arg f_{t}(z)=\alpha\right\} \tag{7}
\end{equation*}
$$

is obtained also by $f_{t_{0}}$.
According to Lemma 1 we discuss $t \in[0,1]$ only.
Denote by $h(t, \varphi)$ the function we are minimizing, i.e.
$h(t, \varphi)=\frac{1}{4}\left|f_{t}\left(r e^{i \varphi}\right)\right|^{-2}=\frac{1}{4}\left|r e^{i \varphi}+\frac{1}{r} e^{-i \varphi}-2 t\right|^{2}=t^{2}-2 a t \cos \varphi+a^{2}-\sin ^{2} \varphi$,
with $a=\frac{1}{2}\left(r+\frac{1}{r}\right)>1$.
Since the function $\varphi \mapsto \Gamma(\varphi)=\sin \varphi /(a \cos \varphi-t)$ strictly increases on intervals of the domain of $\Gamma$, the condition $\arg f_{t}\left(r e^{i \varphi}\right)=\alpha$ can be written as follows:

$$
\begin{equation*}
\frac{\sqrt{a^{2}-1} \sin \varphi}{a \cos \varphi-t}=\tan \alpha \quad \text { for } \quad 0<\varphi<\arccos \left(\frac{t}{a}\right) \tag{8}
\end{equation*}
$$

and

$$
\begin{equation*}
0=\alpha \quad \text { for } \quad \varphi=0, \quad \frac{\pi}{2}=\alpha \quad \text { for } \quad \varphi=\arccos \left(\frac{t}{a}\right) \leq \frac{\pi}{2} \tag{9}
\end{equation*}
$$

Let $0<\alpha<\frac{\pi}{2}$. We are going to prove that the minimum of $h$ on the curve (8) is attained outside of the set $\left\{(t, \varphi): 0<t<1,0<\varphi<\arccos \left(\frac{t}{a}\right)\right\}$. On the contrary, if there existed an $\left(t_{0}, \varphi_{0}\right), 0<t_{0}<1,0<\varphi_{0}<$ $\arccos \left(\frac{t_{0}}{a}\right)$, which realizes the minimum (7), then there would be a Lagrange function

$$
H(t, \varphi) \equiv h(t, \varphi)-\lambda\left[\frac{\sqrt{a^{2}-1} \sin \varphi}{a \cos \varphi-t}-\tan \alpha\right]
$$

such that $\frac{\partial H}{\partial t}\left(t_{0}, \varphi_{0}\right)=\frac{\partial H}{\partial \varphi}\left(t_{0}, \varphi_{0}\right)=0$ and $\sqrt{a^{2}-1} \sin \varphi_{0} /\left(a \cos \varphi_{0}-t_{0}\right)=$ $\tan \alpha$. Reducing $\lambda$ from the above system of equalities we get

$$
\left[\left(t_{0}-a \cos \varphi_{0}\right)^{2}+\left(a^{2}-1\right) \sin ^{2} \varphi_{0}\right] \cos \varphi_{0}=0
$$

a contradiction. Thus (7) is equal to
$\min \left\{\frac{1}{4}\left|f_{t}\left(r e^{i \varphi}\right)\right|^{-2}: t(1-t)=0,0<\varphi<\arccos \left(\frac{t}{a}\right), \arg f_{t}\left(r e^{i \varphi}\right)=\alpha\right\}$.
But $0<\varphi<\frac{\pi}{2}, \sqrt{a^{2}-1} \sin \varphi / a \cos \varphi=\tan \alpha$ implies
$\sin \varphi=a \sin \alpha / \sqrt{a^{2}-\cos ^{2} \alpha} \in(0,1) \quad$ and $\quad \frac{1}{4}\left|f_{0}\left(r e^{i \varphi}\right)\right|^{-2}=\frac{a^{2}\left(a^{2}-1\right)}{a^{2}-\cos ^{2} \alpha}$.
Similarly, if $0<\varphi<\arccos \left(\frac{1}{a}\right)$ and $\frac{\sqrt{a^{2}-1} \sin \varphi}{a \cos \varphi-1}=\tan \alpha$, then

$$
\cos \varphi=\frac{1+a \cos \alpha}{a+\cos \alpha} \in\left(\frac{1}{a}, 1\right)
$$

and

$$
\frac{1}{4}\left|f_{1}\left(r e^{i \varphi}\right)\right|^{-2}=\left(\frac{a^{2}-1}{a+\cos \alpha}\right)^{2}<\frac{a^{2}\left(a^{2}-1\right)}{a^{2}-\cos ^{2} \alpha} .
$$

Thus $\left|f_{0}\left(r e^{i \varphi_{0}}\right)\right|<\left|f_{1}\left(r e^{i \varphi_{1}}\right)\right|$ for
$0<\varphi_{0}<\frac{\pi}{2}, 0<\varphi_{1}<\arccos \left(\frac{1}{a}\right), \arg f_{0}\left(r e^{i \varphi_{0}}\right)=\arg f_{1}\left(r e^{i \varphi_{1}}\right)=\alpha$.
In particular,

$$
\begin{aligned}
\max \{|f(z)| & : f \in T,|z|=r, \arg f(z)=\alpha\} \\
& =\left|f_{1}\left(\frac{r\left(1+a \cos \alpha+i \sqrt{a^{2}-1} \sin \alpha\right)}{a+\cos \alpha}\right)\right| .
\end{aligned}
$$

Finally, we should examine two cases: $\alpha=0$ and $\alpha=\frac{\pi}{2}$. For $\alpha=0$ we have $h(t, 0)=(a-t)^{2} \geq h(1,0)$. In the case $\alpha=\frac{\pi}{2}$ we obtain

$$
h(t, \varphi)=\left(a^{2}-1\right)\left(1-\frac{t^{2}}{a^{2}}\right) \geq h(1, \varphi) .
$$

It means that for every function $f \in T$

$$
f\left(\Delta_{r}\right) \cap\{w: \operatorname{Re} w \geq 0\} \subset f_{1}\left(\Delta_{r}\right) \cap\{w: \operatorname{Re} w \geq 0\} .
$$

From the equation $f_{-t}(-z)=-f_{t}(z)$, which is true for the functions of the form (2), we consequently have

$$
f\left(\Delta_{r}\right) \cap\{w: \operatorname{Re} w \leq 0\} \subset f_{-1}\left(\Delta_{r}\right) \cap\{w: \operatorname{Re} w \leq 0\} .
$$

From Theorem 3 we conclude:
Corollary 1. For every function $f \in T$ and $z \in \partial \Delta_{r}$ (i.e. $|z|=r$ ) we have

1. $|f(z)| \leq \frac{r}{(1-r)^{2}}$,
2. $|\operatorname{Re} f(z)| \leq \frac{r}{(1-r)^{2}}$,
3. $|\operatorname{Im} f(z)| \leq \frac{\sqrt{2\left[\left(1+r^{2}\right) \sqrt{1+34 r^{2}+r^{4}}-1+14 r^{2}-r^{4}\right]}\left(\sqrt{1+34 r^{2}+r^{4}}+1+r^{2}\right)}{8\left[\left(1+r^{2}\right) \sqrt{\left.1+34 r^{2}+r^{4}+1-14 r^{2}+r^{4}\right]}\right.}$.

Observe that Theorem 3 still holds for $r=1$.
As it was said, the set $L_{T}(\Delta)$ is the whole complex plane $\mathbf{C}$. It is easy to see that $\Delta$ could be replaced by another set for which the covering domain is still the whole plane.

Let us consider the lens-shaped domain $H$. For $z \in \partial H$ we have $\left|z+\frac{1}{z}\right|=2$ and hence $z+\frac{1}{z}=2 e^{i \varphi}, \varphi \in(-\pi, \pi]$. Therefore, the boundary of the image of H under the function $f_{1}$ is a straight line $\operatorname{Re} w=-\frac{1}{4}$ because $f_{1}(z)=$ $\frac{1}{2\left(e^{i \varphi}-1\right)}=-\frac{1}{4}\left(1+i \cot \frac{\varphi}{2}\right)$. It implies that $f_{1}(H)=\left\{w \in \mathbf{C}: \operatorname{Re} w>-\frac{1}{4}\right\}$. Likewise, it could be shown that $f_{-1}(H)=\left\{w \in \mathbf{C}: \operatorname{Re} w<\frac{1}{4}\right\}$. We have proved:

Theorem 4. $L_{T}(H)=\mathbf{C}$.
The plain question appears: are there other sets $D \subset H, D \neq H$ such that $L_{T}(D)=\mathbf{C}$ or, is there the smallest set $D_{0}$ having this property (in the sense that $L_{T}\left(D_{0}\right)=\mathbf{C}$ and whose every proper subset $D$ satisfies $\left.L_{T}(D) \neq \mathbf{C}\right)$ ?

Let us denote by $E_{a}$ the subset of $\Delta$ such that $z+\frac{1}{z}$ belongs to the exterior of an ellipse $u=2 \cos \tau, v=2 a \sin \tau$, where $a \geq 1, \tau \in(-\pi, \pi]$. Hence

$$
E_{a}=\left\{z \in \Delta:\left|z+\frac{1}{z}+2 i \sqrt{a^{2}-1}\right|+\left|z+\frac{1}{z}-2 i \sqrt{a^{2}-1}\right|>4 a\right\}
$$

In special case $E_{1}=H$.
For $z \in \partial E_{a} \cap\{z: \operatorname{Im} z>0\}$ or equivalently $z+\frac{1}{z}=2(\cos \tau+i a \sin \tau), \tau \in$ $(-\pi, 0)$ we have

$$
f_{1}(z)=-\frac{1}{4\left[1+\left(a^{2}-1\right) \cos ^{2} \frac{\tau}{2}\right]}\left(1+i a \cot \frac{\tau}{2}\right)
$$

and

$$
f_{-1}(z)=\frac{1}{4\left[1+\left(a^{2}-1\right) \sin ^{2} \frac{\tau}{2}\right]}\left(1-i a \tan \frac{\tau}{2}\right)
$$

This yields that $f_{1}\left(E_{a}\right) \supset\{w: \operatorname{Re} w \geq 0\}$ and $f_{-1}\left(E_{a}\right) \supset\{w: \operatorname{Re} w \leq 0\}$, and eventually $f_{1}\left(E_{a}\right) \cup f_{-1}\left(E_{a}\right)=\mathbf{C}$. This could be written in the form:

Theorem 5. For every $a \geq 1$ we have $L_{T}\left(E_{a}\right)=\mathbf{C}$.
Observe that $E_{\infty}=\lim _{a \rightarrow \infty} E_{a}$ is not a domain, and it consists of two disjoined domains $H_{1}$ and $H_{-1}$ given by

$$
\begin{align*}
H_{1} & =\left\{z \in \Delta: \operatorname{Re}\left(z+\frac{1}{z}\right)>2\right\} \quad \text { and } \\
H_{-1} & =\left\{z \in \Delta: \operatorname{Re}\left(z+\frac{1}{z}\right)<-2\right\} \tag{10}
\end{align*}
$$

These sets appear in the known property of typically real functions [2], [6]:

$$
\begin{align*}
& \forall f \in T \quad\left|f_{-1}(z)\right| \leq|f(z)| \leq\left|f_{1}(z)\right| \text { for } z \in H_{1} \quad \text { and } \\
& \forall f \in T \quad\left|f_{1}(z)\right| \leq|f(z)| \leq\left|f_{-1}(z)\right| \text { for } z \in H_{-1} .
\end{align*}
$$

The image of the curve $\partial H_{1}$ under $f_{1}$ coincides with the imaginary axis, as well as the image of the curve $\partial H_{-1}$ under $f_{-1}$. Consequently, $f_{1}\left(H_{1}\right)=$ $\{w: \operatorname{Re} w>0\}$ and $f_{-1}\left(H_{-1}\right)=\{w: \operatorname{Re} w<0\}$.

It is known that these two functions attain the upper and the lower estimate of argument of typically real functions [2]. For this reason there is no function $f \in T$ for which

$$
\begin{aligned}
& |\arg f(z)| \leq\left|\arg f_{1}(z)\right|=\frac{\pi}{2} \text { for } z \in \partial H_{1} \quad \text { and } \\
& |\arg f(z)| \geq\left|\arg f_{-1}(z)\right|=\frac{\pi}{2} \text { for } z \in \partial H_{-1} .
\end{aligned}
$$

This leads to the conclusion:

## Theorem 6.

$$
L_{T}\left(H_{1} \cup H_{-1}\right)=\mathbf{C} \backslash\{i t: t \in \mathbf{R}\}, \quad L_{T}\left(\operatorname{cl}\left(H_{1} \cup H_{-1}\right)\right)=\mathbf{C},
$$

where $\operatorname{cl}(A)$ stands for a closure of a set $A$.
This theorem provides that the set $\operatorname{cl}\left(H_{1} \cup H_{-1}\right)$ is the smallest set having the covering set equal to the whole plane (because there does not exist a set $D \subset \operatorname{cl}\left(H_{1} \cup H_{-1}\right), D \neq \operatorname{cl}\left(H_{1} \cup H_{-1}\right)$ such that $\left.L_{T}(D)=\mathbf{C}\right)$.

In the above presented results we have found a covering set over a given set $D \subset \Delta$. One can research these domains from another angle. Assume that $\Omega$ is a covering domain over some domain $D$. Our aim is to find $D$.

This problem is easy to solve when $\Omega=\Delta_{M}$. If $L_{T}(D)=\Delta_{M}, M>0$, then every boundary point of $\Delta_{M}$ is attained by some function of the form (2). Certainly, both statements are equivalent: $\left|f_{t}(z)\right|<M, t \in[-1,1]$ and $\left|z+\frac{1}{z}-2 t\right|>\frac{1}{M}, t \in[-1,1]$, which we can rewrite as a system of conditions

$$
\begin{aligned}
\left|z+\frac{1}{z}+2\right| & >\frac{1}{M} \text { for } z \in \Delta, \operatorname{Re}\left(z+\frac{1}{z}\right)<-2 \\
\left|\operatorname{Im}\left(z+\frac{1}{z}\right)\right| & >\frac{1}{M} \text { for } z \in \Delta,\left|\operatorname{Re}\left(z+\frac{1}{z}\right)\right| \leq 2 \\
\left|z+\frac{1}{z}-2\right| & >\frac{1}{M} \text { for } z \in \Delta, \operatorname{Re}\left(z+\frac{1}{z}\right)>2
\end{aligned}
$$

Let us denote by $D_{M}, M>0$ the set

$$
\begin{aligned}
\left\{z \in \Delta:\left|z+\frac{1}{z}-2\right|\right. & \left.>\frac{1}{M}, \operatorname{Re}\left(z+\frac{1}{z}\right)>2\right\} \\
& \cup\left\{z \in \Delta:\left|z+\frac{1}{z}+2\right|>\frac{1}{M}, \operatorname{Re}\left(z+\frac{1}{z}\right)<-2\right\} \\
& \cup\left\{z \in \Delta:\left|\operatorname{Im}\left(z+\frac{1}{z}\right)\right|>\frac{1}{M},\left|\operatorname{Re}\left(z+\frac{1}{z}\right)\right| \leq 2\right\}
\end{aligned}
$$

Using the introduced notation we have

$$
\begin{aligned}
D_{M}=\left\{z \in H_{1}:|z-1|^{2}\right. & \left.>\frac{1}{M}|z|\right\} \cup\left\{z \in H_{-1}:|z+1|^{2}>\frac{1}{M}|z|\right\} \\
& \cup\left\{z \in \Delta \backslash\left(H_{1} \cup H_{-1}\right):\left|\operatorname{Im}\left(z+\frac{1}{z}\right)\right|>\frac{1}{M}\right\}
\end{aligned}
$$

Then
Theorem 7. $L_{T}\left(D_{M}\right)=\Delta_{M}$.
Koebe domains $\boldsymbol{K}_{\boldsymbol{T}}(\boldsymbol{D})$. The minimum of modulus of typically real functions for a fixed $z \in \Delta$ is attained by the functions of the form (4), which are not univalent (except for $f_{1}$ and $f_{-1}$ ). It means that calculating this minimum in all directions $e^{i \alpha}$ is not the same as finding the Koebe domain. This is the reason why the determination of Koebe domains for the class $T$ is usually more difficult than the determination of covering domains. According to Goodman [3], the boundary of the Koebe domain over $\Delta$ consists of the images of points on the unit circle under infinite-valent functions that are called the universal typically real functions.

We will avoid the problem of not univalent functions if we consider the Koebe domain over the lens-shaped domain $H$ and over disks $\Delta_{r}$ with sufficiently small radius (i.e. $r \leq \sqrt{2}-1$ ).

Theorem 8. $K_{T}(H)=\Delta_{\frac{1}{4}}$.
Proof. Set $\Gamma=\partial H \backslash\{-1,1\}, \Gamma_{+}=\{z \in \Gamma: \operatorname{Im} z>0\}, \Gamma_{-}=\{z \in$ $\Gamma: \operatorname{Im} z<0\}$. We shall find the envelope of the family of line segments $\left\{\alpha f_{1}(z)+(1-\alpha) f_{-1}(z): 0<\alpha<1\right\}, z \in \Gamma$.

Let $z \in \Gamma_{+}$which is the same as $z+\frac{1}{z}=2 e^{i \varphi}, \varphi \in(-\pi, 0)$. The complex parametric equation of each line segment connecting $f_{1}(z)$ and $f_{-1}(z)$ is as follows

$$
w(t)=\frac{1}{2\left(e^{i \varphi}-1\right)}+t\left[\frac{1}{2\left(e^{i \varphi}+1\right)}-\frac{1}{2\left(e^{i \varphi}-1\right)}\right], t \in[0,1], \varphi \in(-\pi, 0),
$$

and the real parametric equation is of the form

$$
\left\{\begin{array}{l}
x(t)=-\frac{1}{4}+\frac{1}{2} t \\
y(t)=-\frac{1}{4} \cot \frac{\varphi}{2}+\frac{1}{2} t \cot \varphi, t \in[0,1], \varphi \in(-\pi, 0)
\end{array}\right.
$$

Hence, we have one parameter family of segments given by $y=-\frac{1}{4} \cot \frac{\varphi}{2}+$ $\left(x+\frac{1}{4}\right) \cot \varphi$, where $x \in\left[-\frac{1}{4}, \frac{1}{4}\right]$.

Reducing $\varphi$ from the system

$$
\left\{\begin{array}{l}
y=-\frac{1}{4} \cot \frac{\varphi}{2}+\left(x+\frac{1}{4}\right) \cot \varphi \\
0=\frac{1}{8} \frac{1}{\sin ^{2} \frac{\varphi}{2}}-\left(x+\frac{1}{4}\right) \frac{1}{\sin ^{2} \varphi}
\end{array}\right.
$$

we obtain the envelope of this family satisfying the equation $x^{2}+y^{2}=\frac{1}{16}$. Since $x \in\left[-\frac{1}{4}, \frac{1}{4}\right]$, we conclude that $\partial \Delta_{\frac{1}{4}} \cap\{w: \operatorname{Im} w>0\}$ is the investigated envelope. Clearly, the envelope of this family for $z \in \Gamma_{-}$is $\partial \Delta_{\frac{1}{4}} \cap\{w$ : $\operatorname{Im} w<0\}$.

From the above and from Theorem B it follows that for a fixed $z \in \Gamma$ :

$$
\begin{aligned}
& \{f(z): f \in T\} \cap \Delta_{\frac{1}{4}}=\emptyset \quad \Rightarrow \quad \forall_{f \in T} f(\Gamma) \cap \Delta_{\frac{1}{4}}=\emptyset \\
& \quad \Rightarrow \quad \forall_{f \in T} \Delta_{\frac{1}{4}} \subset f(H) \quad \Rightarrow \quad \Delta_{\frac{1}{4}} \subset K_{T}(H) .
\end{aligned}
$$

All typically real functions are univalent in $H$, see [3], hence for any $f \in T$ we have $f(\Gamma) \subset \partial f(H)$. It means that for an arbitrary point $w,|w|=\frac{1}{4}$, there exists the only one function $f \in T$ such that $w \in \partial f(H)$. It is that function of the form (4) for which the segment $\left[f_{-1}(z), f_{1}(z)\right]$ is tangent to the derived envelope for all $z \in \Gamma$. Hence $K_{T}(H) \subset \Delta_{\frac{1}{4}}$.

Remark. The relation $K_{T}(H) \subset \Delta_{\frac{1}{4}}$ can be proved in another way. One can check that

$$
\partial \Delta_{\frac{1}{4}} \cap\{w: \operatorname{Im} w \geq 0\}=\left\{\alpha f_{1}\left(z_{\alpha}\right)+(1-\alpha) f_{-1}\left(z_{\alpha}\right): \alpha \in[0,1]\right\}
$$

where $z_{\alpha}$ is the only solution of $\alpha f_{1}^{\prime}(z)+(1-\alpha) f_{-1}^{\prime}(z)=0$ in the set $\Delta \cap\{z: \operatorname{Im} z \geq 0\}$.

From the property 4 of Theorem 1 it follows that the set $K_{T}(H)=\Delta_{\frac{1}{4}}$ is contained in $K_{T}(\Delta)$. Theorem 8 states that $K_{T}(H) \neq K_{T}(\Delta)$. Both domains have only two common boundary points $z=1$ and $z=-1$. Let us recall the known result of Brannan and Kirwan [1]:

Theorem C (Brannan, Kirwan). If $f \in T$, then $\Delta_{\frac{1}{4}} \subset f(\Delta)$.
We can improve this result as follows.

Theorem 9. If $f \in T$, then $\Delta_{\frac{1}{4}} \subset f(H)$.
Moreover, we can establish more general version of Theorem 8 concerning sets $E_{a}, a>1$.

Theorem 10. For any $a \geq 1$ the set $K_{T}\left(E_{a}\right)$ is the convex domain having the boundary curve of the form $16 x^{2}+\frac{4\left(1+a^{2}\right)^{2}}{a^{2}} y^{2}=1$.
Proof. Let $z \in \partial E_{a} \cap\{z: \operatorname{Im} z>0\}$. Then $z+\frac{1}{z}=2(\cos \tau+i a \sin \tau)$, $\tau \in(-\pi, 0)$. The line segment connecting $f_{1}(z)$ and $f_{-1}(z)$ is given by the complex parametric equation

$$
w(t)=\frac{-1}{2 \sin \tau\left(\tan \frac{\tau}{2}-a i\right)}+t \frac{1}{\sin ^{2} \tau\left(\cot \frac{\tau}{2}+a i\right)\left(\tan \frac{\tau}{2}-a i\right)}, t \in[0,1]
$$

or by the real parametric equation

$$
\left\{\begin{array}{l}
x(t)=-\frac{1}{4\left[1+\left(a^{2}-1\right) \cos ^{2} \frac{\tau}{2}\right]}+t \frac{1+a^{2}}{4\left[1+\left(a^{2}-1\right) \sin ^{2} \frac{\tau}{2}\right]\left[1+\left(a^{2}-1\right) \cos ^{2} \frac{\tau}{2}\right]} \\
y(t)=-\frac{2 a \cot \frac{\tau}{2}}{4 \tan \frac{\tau}{2}\left[1+\left(a^{2}-1\right) \cos ^{2} \frac{\tau}{2}\right]}+t \frac{1}{4\left[1+\left(a^{2}-1\right) \sin ^{2} \frac{\tau}{2}\right]\left[1+\left(a^{2}-1\right) \cos ^{2} \frac{\tau}{2}\right]}
\end{array}\right.
$$

After simple calculation we can write the equation of one parameter family of line segments

$$
2 a x \cos \tau-\left(1+a^{2}\right) y \sin \tau-\frac{a}{2}=0
$$

From the system

$$
\left\{\begin{array}{c}
2 a x \cos \tau-\left(1+a^{2}\right) y \sin \tau-\frac{a}{2}=0 \\
-2 a x \sin \tau-\left(1+a^{2}\right) y \cos \tau=0
\end{array}\right.
$$

one can obtain the equation of envelope

$$
\begin{equation*}
16 x^{2}+\frac{4\left(1+a^{2}\right)^{2}}{a^{2}} y^{2}=1 \tag{12}
\end{equation*}
$$

Since $t \in[0,1]$ is equivalent to $x \in\left[-\frac{1}{4}, \frac{1}{4}\right]$, we conclude that whole curve (12) is the envelope of the considered family of line segments.

From the convexity of the set $16 x^{2}+\frac{4\left(1+a^{2}\right)^{2}}{a^{2}} y^{2}<1$, from univalence of all typically real functions in each $E_{a}, a \geq 1$ (because $E_{a} \subset H$ ) and the argument similar to that given in the proof of Theorem 8 we obtain $K_{T}\left(E_{a}\right)=\left\{(x, y): 16 x^{2}+\frac{4\left(1+a^{2}\right)^{2}}{a^{2}} y^{2}<1\right\}$.

Corollary 2. $K_{T}\left(E_{\infty}\right)=\emptyset$.
The above presented method of determining an envelope is also suitable for $a \in(0,1)$. In this case, sets $E_{a}$ contain $H$, the domain of univalence and local univalence for the class $T$. Therefore, envelopes obtained in this way do not coincide with the boundary curves of the Koebe domains over $E_{a}, a \in(0,1)$. From the equation (12) we know that the sets bounded by
these envelopes, which can be written as $L_{T}\left(E_{a}\right) \backslash L_{T}\left(\partial E_{a}\right)$, are contained in $\Delta_{\frac{1}{4}}$. It means that the presented method of envelopes fails for determining the sets $E_{a}, 0<a<1$.

Finally, let us consider the Koebe domains over $\Delta_{r}, r \in(0, \sqrt{2}-1]$. The method of an envelope is still good for deriving $K_{T}\left(\Delta_{r}\right)$. Similarly to the argument given above, this method works for any $r \in(0,1)$, but an envelope obtained in this way would be the boundary of the Koebe domain only for such a disk, in which all typically real functions (among other functions (4), too) are univalent. It holds only for $r \leq \sqrt{2}-1$.

For a fixed $r \in(0,1]$ we use the notation

$$
\begin{gathered}
w_{-1}(\varphi)=f_{-1}\left(r e^{i \varphi}\right) \quad, \quad w_{1}(\varphi)=f_{1}\left(r e^{i \varphi}\right) \\
v(\varphi)=\left[\frac{\cos \varphi}{2\left(r+\frac{1}{r}\right)}+\frac{\left(\frac{1}{r}-r\right)^{2} \sin ^{2} \varphi \cos \varphi}{\left(r+\frac{1}{r}\right)\left(r^{2}+\frac{1}{r^{2}}-2 \cos 2 \varphi\right)}\right]+i \frac{\left(\frac{1}{r}-r\right) \sin ^{3} \varphi}{r^{2}+\frac{1}{r^{2}}-2 \cos 2 \varphi}
\end{gathered}
$$

and

$$
w(\varphi)= \begin{cases}w_{-1}(\varphi), & \varphi \in\left[0, \varphi_{0}(r)\right]  \tag{13}\\ v(\varphi), & \varphi \in\left(\varphi_{0}(r), \frac{\pi}{2}\right]\end{cases}
$$

where $\varphi_{0}(r)=\arccos \frac{1}{4}\left[\sqrt{\left(r+\frac{1}{r}\right)^{2}+32}-\left(r+\frac{1}{r}\right)\right]$.
From now on we make the assumption:

$$
\begin{gathered}
\arg w_{-1}(0)=0 \quad, \quad \arg v(0)=0 \quad, \quad \arg w_{1}(0)=0, \\
\quad \arg \left[w_{1}(0)-w_{-1}(0)\right]=0 \quad, \quad \arg w_{-1}^{\prime}(0)=\frac{\pi}{2} .
\end{gathered}
$$

Theorem 11. The domain $K_{T}\left(\Delta_{r}\right)$ for $r \in(0, \sqrt{2}-1]$ is symmetric with respect to both axes with $w=0$ belonging to it. Its boundary in the first quadrant of the complex plane is the curve of the form $w\left(\left[0, \frac{\pi}{2}\right]\right)$.

The proof is based on the following four lemmas.
Lemma 2. The function $\arg w_{-1}^{\prime}(\varphi)$

1. is increasing in $[0, \pi]$ for $r \in(0,2-\sqrt{3}]$,
2. is decreasing in $\left[0, \varphi_{1}(r)\right]$ and is increasing in $\left[\varphi_{1}(r), \pi\right]$ for $r \in(2-$ $\sqrt{3}, 1]$,
where $\varphi_{1}(r)=\arccos \frac{1+r^{2}}{4 r}$.
Proof. Let $h(\varphi)=\left(\arg w_{-1}^{\prime}(\varphi)\right)^{\prime}$. We have

$$
\begin{aligned}
h(\varphi) & =\operatorname{Re}\left(1+r e^{i \varphi} \frac{f_{-1}^{\prime \prime}\left(r e^{i \varphi}\right)}{f_{-1}^{\prime}\left(r e^{i \varphi}\right)}\right)=\operatorname{Re} \frac{1-4 r e^{i \varphi}+r^{2} e^{2 i \varphi}}{1-r^{2} e^{2 i \varphi}} \\
& =\frac{1}{\left|1-r^{2} e^{2 i \varphi}\right|^{2}}\left(1-r^{2}\right)\left(1-4 r \cos \varphi+r^{2}\right) .
\end{aligned}
$$

For $r \in(0,2-\sqrt{3}]$ the function $h$ is positive for all $\varphi \in[0, \pi]$, and for $r \in(2-$ $\sqrt{3}, 1]$ the function $h$ is negative in $\left[0, \varphi_{1}(r)\right)$ and positive in $\left(\varphi_{1}(r), \pi\right]$.

Lemma 3. For $\varphi \in\left[0, \varphi_{0}(r)\right)$ we have

$$
\arg w_{-1}^{\prime}(\varphi)-\arg \left[w_{1}(\varphi)-w_{-1}(\varphi)\right]>0
$$

Proof. Let $h(\varphi)=\arg w_{-1}^{\prime}(\varphi)-\arg \left[w_{1}(\varphi)-w_{-1}(\varphi)\right]$. Then

$$
\begin{aligned}
h(\varphi) & =\arg \left[\frac{1-z}{(1+z)^{3}} i z\right]-\arg \left[\frac{z}{(1-z)^{2}}-\frac{z}{(1+z)^{2}}\right] \\
& =\arg \frac{1-z}{1+z}-\arg \frac{z}{(1-z)^{2}}+\frac{\pi}{2} \\
& =\frac{\pi}{2}-\left[\arctan \frac{2 r \sin \varphi}{1-r^{2}}+\arctan \frac{\left(1-r^{2}\right) \sin \varphi}{\left(1+r^{2}\right) \cos \varphi-2 r^{2}}\right]
\end{aligned}
$$

From the equation $h(\varphi)=0$ it follows that $2 \cos ^{2} \varphi+\left(r+\frac{1}{r}\right) \cos \varphi-4=0$. Therefore, $\varphi=\varphi_{0}(r)$ is the only solution of $h(\varphi)=0$ in $\left[0, \frac{\pi}{2}\right]$. Since $h(0)>0$, so $h(\varphi)>0$ for $\varphi \in\left[0, \varphi_{0}(r)\right)$.

Lemma 4. The envelope of the family of line segments $\left[w_{-1}(\varphi), w_{1}(\varphi)\right]$, where $\varphi \in(0, \pi)$, coincides with $v\left(\left[\varphi_{0}(r), \pi-\varphi_{0}(r)\right]\right)$.
Proof. We begin with calculating the envelope of the family of straight lines containing these segments. We have an equation of these lines:

$$
x\left(\frac{1}{r^{2}}-r^{2}\right) \sin 2 \varphi+y\left[2-\left(\frac{1}{r^{2}}+r^{2}\right) \cos 2 \varphi\right]=\left(\frac{1}{r}-r\right) \sin \varphi
$$

From

$$
\left\{\begin{array}{l}
x\left(\frac{1}{r^{2}}-r^{2}\right) \sin 2 \varphi+y\left[2-\left(\frac{1}{r^{2}}+r^{2}\right) \cos 2 \varphi\right]-\left(\frac{1}{r}-r\right) \sin \varphi=0 \\
2 x\left(\frac{1}{r^{2}}-r^{2}\right) \cos 2 \varphi+2 y\left(\frac{1}{r^{2}}+r^{2}\right) \sin 2 \varphi-\left(\frac{1}{r}-r\right) \cos \varphi=0
\end{array}\right.
$$

we obtain the envelope which can be written in the form $w=v(\varphi), \varphi \in$ $(0, \pi)$, where $v$ is defined by $(12)$. This curve is regular because $\left(\operatorname{Re} v^{\prime}(\varphi)\right)^{2}+$ $\left(\operatorname{Im} v^{\prime}(\varphi)\right)^{2} \neq 0$, which can be concluded from the fact that the system

$$
\left\{\begin{array}{l}
\operatorname{Re} v^{\prime}(\varphi)=0 \\
\operatorname{Im} v^{\prime}(\varphi)=0
\end{array}\right.
$$

has no solution for $\varphi \in(0, \pi)$.
Moreover, observe

$$
\arg \left[w_{1}(\varphi)-w_{-1}(\varphi)\right]=2 \arg \frac{r e^{i \varphi}}{1-r^{2} e^{2 i \varphi}}
$$

hence starlikeness of the function $z \rightarrow \frac{z}{1-z^{2}}$ implies that the argument of the tangent vector to the curve $v((0, \pi))$ is increasing.

The envelope of the family of line segments is constructed of these points of $v((0, \pi))$ for which

$$
\arg w_{-1}(\varphi) \leq \arg v(\varphi) \leq \arg w_{1}(\varphi)
$$

or equivalently

$$
\operatorname{Im} w_{-1}(\varphi) \leq \operatorname{Im} v(\varphi) \leq \operatorname{Im} w_{1}(\varphi) \quad \text { for } \quad \varphi \in\left(0, \frac{\pi}{2}\right]
$$

and

$$
\operatorname{Im} w_{-1}(\varphi) \geq \operatorname{Im} v(\varphi) \geq \operatorname{Im} w_{1}(\varphi) \quad \text { for } \quad \varphi \in\left[\frac{\pi}{2}, \pi\right)
$$

For $\varphi \in(0, \pi)$ we have

$$
\frac{1}{r+\frac{1}{r}+2|\cos \varphi|} \leq \frac{\sin ^{2} \varphi}{r+\frac{1}{r}-2|\cos \varphi|},
$$

and hence

$$
2 \cos ^{2} \varphi+\left(r+\frac{1}{r}\right) \cos \varphi-4 \leq 0
$$

and finally

$$
\varphi \in\left[\varphi_{0}(r), \pi-\varphi_{0}(r)\right]
$$

We have proved that the envelope of the family of line segments $\left[w_{-1}(\varphi), w_{1}(\varphi)\right]$ and the curve $v\left(\left[\varphi_{0}(r), \pi-\varphi_{0}(r)\right]\right)$ are the same.

Let $A_{\varphi}, \varphi \in\left(0, \frac{\pi}{2}\right]$ be the sector given by

$$
A_{\varphi}=\left\{u \in \mathbf{C}: \arg w_{-1}(\varphi) \leq \arg \left[u-w_{-1}(\varphi)\right] \leq \arg \left[w_{1}(\varphi)-w_{-1}(\varphi)\right]\right\}
$$

and let

$$
\begin{aligned}
& l_{1}=\left\{u \in \mathbf{C}: \arg u=\arg w_{-1}(\varphi)\right\} \\
& l_{2}=\left\{u \in \mathbf{C}: \arg u=\arg \left[w_{1}(\varphi)-w_{-1}(\varphi)\right]\right\}
\end{aligned}
$$

Denote by $E$ the domain which is bounded, symmetric with respect to both axes and whose boundary in the first quadrant of the complex plane is identical with $w\left(\left[0, \frac{\pi}{2}\right]\right)$.
Lemma 5. For $\varphi \in\left[0, \frac{\pi}{2}\right]$ we have

1. $E \cap A_{\varphi}=\emptyset$,
2. $\operatorname{cl}(E) \cap A_{\varphi}$ is a one-point set.

Proof. Observe that from Lemma 2 the curve $w\left(\left[0, \frac{\pi}{2}\right]\right)$ has only one inflexion point $w\left(\varphi_{1}\right)$ when $r \in(2-\sqrt{3},(\sqrt{24}-\sqrt{15}) / 3)$ and $w\left(\varphi_{0}\right)$ if $r \in$ $((\sqrt{24}-\sqrt{15}) / 3, \sqrt{2}-1]$.

Let us discuss the case $r \in(2-\sqrt{3},(\sqrt{24}-\sqrt{15}) / 3)$. Let $\varphi \in\left(0, \varphi_{1}(r)\right]$. From Lemma 2, Lemma 3 and monotonicity of $\arg \left[w_{1}(\varphi)-w_{-1}(\varphi)\right]$ we conclude

$$
\begin{aligned}
A_{\varphi} & \subset\left\{u \in \mathbf{C}: \arg w_{-1}(\varphi) \leq \arg \left[u-w_{-1}(\varphi)\right] \leq \arg \left[w_{1}\left(\varphi_{1}\right)-w_{-1}\left(\varphi_{1}\right)\right]\right\} \\
& \subset\left\{u \in \mathbf{C}: \arg w_{-1}(\varphi) \leq \arg \left[u-w_{-1}(\varphi)\right] \leq \arg w_{-1}^{\prime}\left(\varphi_{1}\right)\right\}
\end{aligned}
$$

It means that $A_{\varphi} \cap f_{-1}\left(\Delta_{r}\right)=\emptyset$ and hence $A_{\varphi} \cap E=\emptyset$, since $E \subset f_{-1}\left(\Delta_{r}\right)$. Let $\varphi \in\left(\varphi_{1}(r), \varphi_{0}(r)\right]$. From Lemma 2 and Lemma 3 we have

$$
A_{\varphi} \subset\left\{u \in \mathbf{C}: \arg w_{-1}(\varphi) \leq \arg \left[u-w_{-1}(\varphi)\right] \leq \arg w_{-1}^{\prime}(\varphi)\right\} .
$$

It means that $A_{\varphi} \cap f_{-1}\left(\Delta_{r}\right)=\emptyset$ and hence $A_{\varphi} \cap E=\emptyset$, since $E \subset f_{-1}\left(\Delta_{r}\right)$. Furthermore, $\operatorname{cl}(E) \cap A_{\varphi}=w_{-1}(\varphi)$ for $\varphi \in\left(0, \varphi_{0}\right]$.
Let $\varphi \in\left(\varphi_{0}, \frac{\pi}{2}\right]$. Then $l_{2}$ is tangent to $w\left(\left(\varphi_{0}, \frac{\pi}{2}\right)\right)$. From starlikeness of $f_{-1}$ and the definition of $E$ it follows that $w_{-1}(\varphi) \notin E$ and consequently $A_{\varphi} \cap E=\emptyset$. The sets $\operatorname{cl}(E)$ and $A_{\varphi}$ have only one common point, i.e. the tangential point.

In the case $r \in(0,2-\sqrt{3})$ and $r \in(\sqrt{24}-\sqrt{15}) / 3, \sqrt{2}-1]$ lemma can be proved slightly more easily, proceeding analogously to the case proven above, dividing the segment $\left[0, \frac{\pi}{2}\right]$ into two $\left[0, \varphi_{0}(r)\right]$ and $\left(\varphi_{0}(r), \frac{\pi}{2}\right]$.

Proof of Theorem 11. Let $r \in(0, \sqrt{2}-1]$. From Lemma 5 it follows that $E \subset K_{T}\left(\Delta_{r}\right)$. The definition of the Koebe domain leads to

$$
K_{T}\left(\Delta_{r}\right) \subset \bigcap_{\alpha \in[0,1]}\left(\alpha f_{1}+(1-\alpha) f_{-1}\right)\left(\Delta_{r}\right)=E .
$$

Hence $K_{T}\left(\Delta_{r}\right)=E$.

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Leopold Koczan
Department of Applied Mathematics Lublin University of Technology
ul. Nadbystrzycka 38D 20-618 Lublin, Poland e-mail: l.koczan@pollub.pl

Paweł Zaprawa
Department of Applied Mathematics
Lublin University of Technology
ul. Nadbystrzycka 38D
20-618 Lublin, Poland
e-mail: p.zaprawa@pollub.pl


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